

Approximation and Furi–Pera Type Theorems for the S-KKM Class

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Received January 11, 2004

Revised September 6, 2004

Abstract. Leray–Schauder alternatives, Furi–Pera type fixed point and Fan type approximation results are established for multimaps in the S-KKM class.

1. Introduction

This paper discusses new fixed point results of Furi–Pera type [7] for the S-KKM multimaps. In the process we establish new Leray–Schauder alternatives for S-KKM multimaps defined on closed, convex, normal subsets of locally convex Hausdorff topological vector spaces. We also obtain several approximation results of Fan type. Furi–Pera type results were given for \mathfrak{A}_c^k and other classes in [2, 9, 10]. On the other hand, Fan type approximation [6] results were proved for \mathfrak{A}_c^k and other classes in [8, 13, 14]. As a generalization of the \mathfrak{A}_c^k class, the class of S-KKM maps was introduced and studied by Chang et al. [4] and further investigated by Agarwal and O’Regan [1], Chang et al. [3], O’Regan, Shahzad and Agarwal [12], and Shahzad [17]. Our results extend and complement those in [1–4, 7–10, 13, 14].

2. Preliminaries

Let E and E_1 be Hausdorff topological vector spaces. Recall a polytope P in E_1

is any convex hull of a nonempty finite subset of E_1 . Given a class \mathcal{X} of maps, $\mathcal{X}(E_1, E)$ denotes the set of maps $F : E_1 \rightarrow 2^E$ (the nonempty subsets of E) belonging to \mathcal{X} , and \mathcal{X}_c the set of finite compositions of maps in \mathcal{X} . A class \mathfrak{A} of maps [15, 16] is defined by the following properties:

- (i) \mathfrak{A} contains the class \mathcal{C} of single valued continuous functions;
- (ii) each $F \in \mathfrak{A}_c$ is upper semicontinuous and compact valued; and
- (iii) for any polytope P , $F \in \mathfrak{A}_c(P, P)$ has a fixed point, where the intermediate spaces of composites are suitably chosen for each \mathfrak{A} .

Definition 2.1. $F \in \mathfrak{A}_c^k(E_1, E)$ (i.e. F is \mathfrak{A}_c^k -admissible) if for any compact subset K of E_1 , there is a $G \in \mathfrak{A}_c(K, E)$ with $G(x) \subseteq F(x)$ for each $x \in K$.

Definition 2.2. Let X be a convex subset of a Hausdorff topological vector space and Y a topological space. If $S, T : X \rightarrow 2^Y$ are two set-valued maps such that $T(\text{co}(A)) \subseteq S(A)$ for each finite subset A of X , then we say that S is a generalized KKM map w.r.t. T . The map $T : X \rightarrow 2^Y$ is said to have the KKM property if for any generalized KKM w.r.t. T map S , the family

$$\{\overline{S(x)} : x \in X\}$$

has the finite intersection property. We let

$$\text{KKM}(X, Y) = \{T : X \rightarrow 2^Y : T \text{ has the KKM property}\}.$$

Remark 2.1. If X is a convex space, then $\mathfrak{A}_c^k(X, Y) \subset \text{KKM}(X, Y)$ (see [5]).

Definition 2.3. Let X be a nonempty set, Y a nonempty convex subset of a Hausdorff topological vector space and Z a topological space. If $S : X \rightarrow 2^Y$, $T : Y \rightarrow 2^Z$, $F : X \rightarrow 2^Z$ are three set-valued maps such that $T(\text{co}(S(A))) \subseteq F(A)$ for each nonempty finite subset A of X , then F is called a generalized S -KKM map w.r.t. T . If the map $T : X \rightarrow 2^Z$ is such that for any generalized S -KKM w.r.t. T map F , the family

$$\{\overline{F(x)} : x \in X\}$$

has the finite intersection property, then T is said to have the S -KKM property. The class

$$\text{dis } S\text{-KKM}(X, Y, Z) = \{T : Y \rightarrow 2^Z : T \text{ has the } S\text{-KKM property}\}.$$

Remark 2.2. Note that $S\text{-KKM}(X, Y, Z) = \text{KKM}(X, Z)$ whenever $X = Y$ and S is the identity mapping $\mathbf{1}_X$. Moreover, $\text{KKM}(Y, Z)$ is contained in $S\text{-KKM}(X, Y, Z)$ for any $S : X \rightarrow 2^Y$ and usually this inclusion is proper (see [4, p. 214-215]). $S\text{-KKM}(X, Y, Z)$ also includes other important classes of multimaps (see [3, 4] for examples).

Remark 2.3. Let X be a convex space, Y a convex subset of a Hausdorff locally convex space, and Z a normal space. Suppose $s : Y \rightarrow Y$ is surjective, $F \in s\text{-KKM}(Y, Y, Z)$ is closed, and $f \in \mathcal{C}(X, Y)$. Then $Ff \in \mathbf{1}_X\text{-KKM}(X, X, Z)$ (see [4]).

Remark 2.4. Let X be a convex subset of a Hausdorff topological space, Y a convex space, and Z, W topological spaces and $S : X \rightarrow 2^Y$. If $F \in S\text{-KKM}(X, Y, Z)$ and $f \in \mathcal{C}(Z, W)$, then $f \circ F \in S\text{-KKM}(X, Y, W)$ (see [4]).

Let (E, d) be a pseudometric space. For any $C \subseteq E$, let $B(C, \epsilon) = \{x \in E : d(x, C) \leq \epsilon\}$, here $\epsilon > 0$. The measure of noncompactness of the set $M \subseteq E$ is defined by $\alpha(M) = \inf Q(M)$, where

$$Q(M) = \{\epsilon > 0 : M \subseteq B(A, \epsilon) \text{ for some finite subset } A \text{ of } E\}.$$

Let C be a subset of a locally convex Hausdorff topological vector space E , and let \mathcal{P} be a defining system of seminorms on E . Suppose $F : C \rightarrow 2^E$. Then F is called countably \mathcal{P} -concentrative mapping if $F(C)$ is bounded, and for $p \in \mathcal{P}$ and each countably bounded subset S of C , we have $\alpha_p(F(S)) \leq \alpha_p(S)$, and for $p \in \mathcal{P}$ for each countably bounded non- p -precompact subset S of C (i.e., S is not precompact in the pseudonormed space (E, p)), we have $\alpha_p(F(S)) < \alpha_p(S)$; here $\alpha_p(\cdot)$ denotes the measure of noncompactness in the pseudonormed space (E, p) .

Let Q be a subset of a Hausdorff topological space X . We let \bar{Q} (respectively, $\partial Q, \text{int}(Q)$) denote the closure (respectively, boundary, interior) of Q .

Let C be a subset of a Hausdorff topological vector space E and $x \in X$. Then the inward set $I_C(x)$ is defined by

$$I_C(x) = \{x + r(y - x) : y \in C, r \geq 0\}.$$

If C is convex and $x \in C$, then

$$I_C(x) = x + \{r(y - x) : y \in C, r \geq 1\}.$$

The following results [1, 10] will be needed in the sequel.

Theorem 2.1. *Let Ω be a closed, convex subset of a locally convex Hausdorff topological vector space E with $x_0 \in \Omega$ and $s : \Omega \rightarrow \Omega$ is surjective. Suppose $F \in s\text{-KKM}(\Omega, \Omega, \Omega)$ is closed with the following property holding:*

$$A \subseteq \Omega, A = \overline{co}(\{x_0\} \cup F(A)) \text{ implies } A \text{ is compact.} \tag{2.1}$$

Then F has a fixed point in Ω .

Theorem 2.2. *Let Ω be a closed, convex subset of a locally convex Hausdorff topological vector space E and $x_0 \in \Omega$ and $s : \Omega \rightarrow \Omega$ is surjective. Suppose $F \in s\text{-KKM}(\Omega, \Omega, \Omega)$ is closed and satisfies the following properties:*

$$A \subseteq \Omega, A = co(\{x_0\} \cup F(A)) \text{ implies } \bar{A} \text{ is compact} \tag{2.2}$$

and

$$F(\bar{A}) \subseteq \overline{F(A)} \text{ for any relatively compact subset } A \text{ of } \Omega. \tag{2.3}$$

Then F has a fixed point in Ω .

Theorem 2.3. *Let Ω be a closed, convex subset of a locally convex Hausdorff topological vector space E and $x_0 \in \Omega$ and $s : \Omega \rightarrow \Omega$ is surjective. Suppose*

$F \in s\text{-KKM}(\Omega, \Omega, \Omega)$ is closed, maps compact sets into relatively compact sets, satisfies (2.3) and suppose the following properties hold:

$$\left\{ \begin{array}{l} A \subseteq \Omega, A = \text{co}(\{x_0\} \cup F(A)) \text{ with } \overline{A} = \overline{C} \\ \text{and } C \subseteq A \text{ countable, implies } \overline{A} \text{ is compact,} \end{array} \right. \quad (2.4)$$

$$\left\{ \begin{array}{l} \text{for any relatively compact subset } A \text{ of } \Omega, \text{ there} \\ \text{exists a countable set } B \subseteq A \text{ with } \overline{B} = \overline{A}, \end{array} \right. \quad (2.5)$$

and

$$\text{if } A \text{ is a compact subset of } \Omega, \text{ then } \overline{\text{co}}(A) \text{ is compact.} \quad (2.6)$$

Then F has a fixed point in Ω .

Remark 2.5. It is worth noting that if E is metrizable, then (2.5) holds, and if E is quasicomplete then (2.6) holds.

Remark 2.6. Following arguments similar to those given in [11, Theorem 2.3], one can remove (2.3) in Theorem 2.2 and Theorem 2.3 for certain subclasses of $s\text{-KKM}$ maps.

Theorem 2.4. *Let Ω be a nonempty, closed, convex subset of a Fréchet space E (\mathcal{P} is a defining system of seminorms) and suppose $F \in \text{KKM}(\Omega, \Omega)$ is a closed, countably \mathcal{P} -concentrative map. Then F has a fixed point in Ω .*

3. Main Results

Our first results are nonlinear alternatives of Leray–Schauder type for maps in the $s\text{-KKM}$ class.

Let C be a convex subset of a Banach space E with $0 \in \text{int}(C)$. The Minkowski functional $\mu : E \rightarrow [0, \infty)$ of C is defined by

$$\mu(x) = \inf\{r > 0 : x \in rC\}.$$

The following properties of the Minkowski functional are well known:

- (i) μ is continuous on E ;
- (ii) $\mu(x + y) \leq \mu(x) + \mu(y), x, y \in E$;
- (iii) $\mu(\lambda x) = \lambda\mu(x), \lambda \geq 0, x \in E$;
- (iv) $0 \leq \mu(x) < 1$ if $x \in \text{int}(C)$;
- (v) $\mu(x) > 1$, if $x \notin \overline{C}$;
- (vi) $\mu(x) = 1$, if $x \in \partial C$.

Theorem 3.1. *Let E be a locally convex Hausdorff topological vector space, C a closed, convex, normal subset of E , $U \subseteq C$ an open convex subset of E , and $0 \in U$. Suppose $s : \overline{U} \rightarrow \overline{U}$ is surjective and $F \in s\text{-KKM}(\overline{U}, \overline{U}, C)$ is closed and satisfies the following two properties:*

$$A \subseteq C, A \subseteq \overline{\text{co}}(\{0\} \cup F(\text{co}(\{0\} \cup A))) \text{ implies } \overline{A} \text{ is compact} \quad (3.1)$$

and

$$x \notin \lambda F(x) \text{ for } x \in \partial U \text{ and } \lambda \in (0, 1). \tag{3.2}$$

Then F has a fixed point in \overline{U} .

Proof. Let μ be the Minkowski functional on \overline{U} and let $r : E \rightarrow \overline{U}$ be given by

$$r(x) = \frac{x}{\max\{1, \mu(x)\}} \text{ for } x \in E. \tag{3.3}$$

Let $G = Fr$. Then, by Remark 2.3, $G \in \mathbf{1}_C\text{-KKM}(C, C, C)$. Furthermore G is closed. Next we claim

$$\text{if } A \subseteq C \text{ and } A \subseteq \overline{\text{co}}(\{0\} \cup G(A)), \text{ then } \overline{A} \text{ is compact.} \tag{3.4}$$

To see this notice if $A \subseteq C$ and $A \subseteq \overline{\text{co}}(\{0\} \cup Fr(A))$, then since $r(A) \subseteq \text{co}(\{0\} \cup A)$ we have

$$A \subseteq \overline{\text{co}}(\{0\} \cup F(\text{co}(\{0\} \cup A))).$$

Now (3.1) implies \overline{A} is compact, so (3.4) holds. Now Theorem 2.1 guarantees that there exists $x \in C$ with $x \in Fr(x)$. If we let $z = r(x) \in \overline{U}$, then $z \in rF(z)$. Thus $z = r(y)$ for some $y \in F(z)$. Now either $y \in \overline{U}$ or $y \notin \overline{U}$. If $y \in \overline{U}$, then $r(y) = y$ so $z = r(y) = y \in F(z)$, and we are finished. If $y \notin \overline{U}$, then $r(y) = \lambda y$ with $\lambda = \frac{1}{\mu(y)} \in (0, 1)$. Thus $z = r(y) = \lambda y \in \lambda F(z)$ with $\lambda \in (0, 1)$. This contradicts (3.2). ■

Theorem 3.2. *Let E be a locally convex Hausdorff topological vector space, C a closed, convex, normal subset of E , $U \subseteq C$ an open convex subset of E , and $0 \in U$. Suppose $s : \overline{U} \rightarrow \overline{U}$ is surjective and $F \in s\text{-KKM}(\overline{U}, \overline{U}, C)$ is closed, satisfies (3.2), and the following properties:*

$$A \subseteq C, A \subseteq \text{co}(\{0\} \cup F(\text{co}(\{0\} \cup A))) \text{ implies } \overline{A} \text{ is compact} \tag{3.5}$$

and

$$F(\overline{A}) \subseteq \overline{F(A)} \text{ for any relatively compact subset } A \text{ of } \overline{U}. \tag{3.6}$$

Then F has a fixed point in \overline{U} .

Proof. Let μ, r, G be as in Theorem 3.1. Essentially the same reasoning as in Theorem 3.1 guarantees that $G \in \mathbf{1}_C\text{-KKM}(C, C, C)$ is closed with

$$\text{if } A \subseteq C \text{ and } A \subseteq \text{co}(\{0\} \cup G(A)), \text{ then } \overline{A} \text{ is compact.} \tag{3.7}$$

Next we claim

$$G(\overline{A}) \subseteq \overline{G(A)} \text{ for any relatively compact subset } A \text{ of } C. \tag{3.8}$$

This is immediate since F satisfies (3.6) and r is continuous i.e. if A is a relatively compact subset of C , then

$$G(\overline{A}) = F(r(\overline{A})) \subseteq F(\overline{r(A)}) \subseteq \overline{F(r(A))} = \overline{G(A)}.$$

Now Theorem 2.2 guarantees that there exists $x \in C$ with $x \in G(x) = Fr(x)$. If we let $z = r(x) \in \bar{U}$, then $z \in rF(z)$. Thus $z = r(y)$ for some $y \in F(z)$ and as in Theorem 3.1 we have $y \in \bar{U}$. Consequently we have $z = r(y) = y \in F(z)$. ■

Essentially the same reasoning as in Theorem 3.2 (except here we use Theorem 2.3) establishes the following result.

Theorem 3.3. *Let E be a locally convex Hausdorff topological vector space, C a closed, convex, normal subset of E , $U \subseteq C$ an open convex subset of E , and $0 \in U$. Suppose $s : \bar{U} \rightarrow \bar{U}$ is surjective and $F \in s\text{-KKM}(\bar{U}, \bar{U}, C)$ is closed, maps compact sets into relatively compact sets. Assume (3.2) and (3.6) are satisfied and also suppose the following properties hold:*

$$\left\{ \begin{array}{l} A \subseteq C, A \subseteq \text{co}(\{0\} \cup F(\text{co}(\{0\} \cup A))) \text{ with } \bar{A} = \bar{Q} \\ \text{and } Q \subseteq A \text{ countable, implies } \bar{A} \text{ is compact,} \end{array} \right. \quad (3.9)$$

$$\left\{ \begin{array}{l} \text{for any relatively compact subset } A \text{ of } C, \text{ there} \\ \text{exists a countable set } B \subseteq A \text{ with } \bar{B} = \bar{A}, \end{array} \right. \quad (3.10)$$

and

$$\text{if } A \text{ is a compact subset of } C, \text{ then } \overline{\text{co}}(A) \text{ is compact.} \quad (3.11)$$

Then F has a fixed point in \bar{U} .

Theorem 3.4. *Let E be a Fréchet space, C a closed, convex, bounded subset of E , $U \subseteq C$ an open convex subset of E , and $0 \in U$. Suppose $s : \bar{U} \rightarrow \bar{U}$ is surjective and $F \in s\text{-KKM}(\bar{U}, \bar{U}, C)$ is a closed countably \mathcal{P} -concentrative map and satisfies (3.2). Then F has a fixed point in \bar{U} .*

Proof. Let μ, r, G be as in Theorem 3.1. Essentially the same reasoning as in Theorem 3.1 guarantees that $G \in \mathbf{1}_C\text{-KKM}(C, C, C)$ is closed. Next we show that G is countably \mathcal{P} -concentrative. Let $p \in \mathcal{P}$ and Ω be a countably bounded non-precompact subset of C . Then since

$$G(\Omega) \subseteq Fr(\Omega) \subseteq F(\text{co}(\Omega \cup \{0\}))$$

we have $\alpha_p(G(\Omega)) < \alpha_p(\Omega)$. Now Theorem 2.4 guarantees that there exists $x \in C$ with $x \in G(x) = Fr(x)$. If we let $z = r(x) \in \bar{U}$, then $z \in rF(z)$ and so $z = r(y)$ for some $y \in F(z)$. As in Theorem 3.1 we have $y \in \bar{U}$. Thus $z = r(y) = y \in F(z)$. ■

Our next result is a Furi–Pera type fixed point theorem for compact, closed s -KKM maps.

Theorem 3.5. *Let Q be a closed convex subset of a metrizable locally convex topological vector space E with $0 \in Q$. Suppose $s : Q \rightarrow Q$ is surjective and $F \in s\text{-KKM}(Q, Q, E)$ is a closed, compact (i.e., $F(Q)$ is a subset of a relatively compact subset of Q) map with the following condition satisfied:*

$$\left\{ \begin{array}{l} \text{if } \{(x_j, \lambda_j)\}_{j=1}^\infty \text{ is a sequence in } \partial Q \times [0, 1] \text{ converging} \\ \text{to } (x, \lambda) \text{ with } x \in \lambda F(x) \text{ and } 0 \leq \lambda < 1, \text{ then} \\ \{\lambda_j F(x_j)\} \subseteq Q \text{ for } j \text{ sufficiently large.} \end{array} \right. \quad (3.12)$$

Then F has a fixed point in Q .

Proof. Let $r : E \rightarrow Q$ be a continuous retraction (the existence of r follows from Dugundji’s extension theorem).

Remark 3.1. If $0 \in \text{int}Q$, we may take

$$r(x) = \frac{x}{\max\{1, \mu(x)\}}, \quad x \in E,$$

where μ is the Minkowski functional on Q . Note if $\text{int}Q = \emptyset$, then $\partial Q = Q$.

From Remark 3.1, we may choose (and we do so) the retraction r above so that $r(z) \in \partial Q$ if $z \in E \setminus Q$. Consider

$$B = \{x \in E : x \in Fr(x)\}.$$

Firstly $B \neq \emptyset$. To see this notice $Fr \in \mathbf{1}_E\text{-KKM}(E, E, E)$ is closed and also notice Fr is a compact map (r is continuous and F is compact). Now [4, Theorem 3.2] guarantees that Fr has a fixed point and so $B \neq \emptyset$. In addition since F is closed we have that B is closed. In fact B is compact since

$$B \subseteq Fr(B) \subseteq F(Q).$$

We claim that $B \cap Q \neq \emptyset$. Suppose not. Then since B is compact and Q is closed there exists a $\delta > 0$ with $\text{dist}(B, Q) > \delta$. Choose $m \in \{1, 2, \dots\}$ with $1 < \delta m$. Define

$$U_i = \left\{ x \in E : d(x, Q) < \frac{1}{i} \right\} \text{ for } i \in \{m, m + 1, \dots\},$$

here d is the metric associated with E [18, p. 18, 29]. Fix $i \in \{m, m + 1, \dots\}$. Since $\text{dist}(B, Q) > \delta$ then we see that $B \cap \overline{U}_i = \emptyset$. In addition U_i is open and convex (follows from the fact that open balls are convex), $0 \in U_i$ and $Fr \in \mathbf{1}_{\overline{U}_i}\text{-KKM}(\overline{U}_i, \overline{U}_i, E)$ is a closed, compact map. Now Theorem 3.1 guarantees, since $B \cap \overline{U}_i = \emptyset$, that there exists

$$(y_i, \lambda_i) \in \partial U_i \times (0, 1) \text{ with } y_i \in \lambda_i Fr(y_i).$$

We can do this for each $i \in \{m, m + 1, \dots\}$. Thus we have

$$\{\lambda_i Fr(y_i)\} \not\subseteq Q \text{ for each } i \in \{m, m + 1, \dots\}. \quad (3.13)$$

We now look at

$$D = \{x \in E : x \in \lambda Fr(x) \text{ for some } \lambda \in [0, 1]\}.$$

Notice $D \neq \emptyset$ is closed and in fact compact (so sequentially compact) since F is a compact map. This together with

$$d(y_j, Q) = \frac{1}{j} \text{ and } |\lambda_j| \leq 1 \text{ for } j \in \{m, m + 1, \dots\}$$

implies that we may assume without loss of generality that

$$\lambda_j \rightarrow \lambda^* \in [0, 1] \text{ and } y_j \rightarrow y^* \in \partial Q.$$

In addition we have $y_j \in \lambda_j Fr(y_j)$ with F closed, and so $y^* \in \lambda^* Fr(y^*)$. Note that $\lambda^* \neq 1$ since $B \cap Q = \emptyset$. Hence $0 \leq \lambda^* < 1$. However (3.12) with

$$x_j = r(y_j) \in \partial Q \text{ and } x = y^* = r(y^*)$$

implies $\{\lambda_j Fr(y_j)\} \subseteq Q$ for j sufficiently large. This contradicts (3.13). Thus $B \cap Q \neq \emptyset$ so there exists $x \in Q$ with $x \in Fr(x) = F(x)$. ■

Theorem 3.6 can be further improved if E is a Hilbert space. In the following result, by a countably condensing map F we mean $\alpha(F(B)) < \alpha(B)$ for all countably bounded sets B of C with $\alpha(B) \neq 0$ and $\alpha(F(D)) \leq \alpha(D)$ for all countably bounded sets D of C , where $\alpha(\cdot)$ is the Kuratowski measure of noncompactness (see [19]).

Theorem 3.6. *Let Q be a closed convex subset of a Hilbert space E with $0 \in Q$. Suppose $s : Q \rightarrow Q$ is surjective and $F \in s\text{-KKM}(Q, Q, E)$ is a closed, countably condensing map with $F(Q)$ a bounded subset of E and assume (3.12) holds. Then F has a fixed point in Q .*

Proof. Define $r : E \rightarrow Q$ by $r(x) = P_Q(x)$ i.e. r is the nearest point projection. Note r is nonexpansive. Let $C_0 = \overline{\text{co}}(F(Q) \cup \{0\})$. Then C_0 is bounded. Now let

$$B = \{x \in E : x \in Fr(x)\}.$$

Then $Fr \in \mathbf{1}_{C_0}\text{-KKM}(C_0, C_0, C_0)$. Next we show Fr is a countably condensing map. Let Ω be any countable subset of C_0 with $\alpha(\Omega) \neq 0$. Clearly $r(\Omega)$ is countable. Consequently, if $\alpha(r(\Omega)) \neq 0$, then

$$\alpha(Fr(\Omega)) < \alpha(r(\Omega)) \leq \alpha(\Omega),$$

whereas if $\alpha(r(\Omega)) = 0$, then

$$\alpha(Fr(\Omega)) < \alpha(r(\Omega)) = 0 < \alpha(\Omega).$$

Now Theorem 2.4 guarantees that Fr has a fixed point so $B \neq \emptyset$. Also B is closed. Next we show B is compact. Indeed, if $\{y_n\}_1^\infty$ is any sequence in B , then $y_n \in Fr(y_n)$, $n = 0, 1, \dots$. Let $C = \{y_n\}_1^\infty$. Then C is countable with $C \subseteq \overline{\text{co}}(Fr(C) \cup \{0\})$. Suppose $\alpha(C) \neq 0$. Then

$$\alpha(C) \leq \alpha(Fr(C)) < \alpha(r(C)) \leq \alpha(C), \text{ if } \alpha(r(C)) \neq 0,$$

whereas

$$\alpha(C) \leq \alpha(Fr(C)) \leq \alpha(r(C)) = 0 < \alpha(C), \text{ if } \alpha(r(C)) = 0.$$

We have a contradiction in both cases. Therefore, $\alpha(C) = 0$ and so \overline{C} is compact. As a result, there exists a subsequence N of $\{1, 2, \dots\}$ and a $y \in \overline{C}$ such that $y_n \rightarrow y$ as $n \rightarrow \infty$ in N . The closedness of F further implies that $y \in Fr(y)$ and so $y \in B = \overline{B}$. As a result B is compact. Suppose now $B \cap Q = \emptyset$. Let m, U_i be as in Theorem 3.5 and essentially the same reasoning as in Theorem 3.5 (since $Fr \in \mathbf{1}_{\overline{U_i}}\text{-KKM}(\overline{U_i}, \overline{U_i}, E)$ is a countably condensing map)(here we have used Theorem 3.4) guarantees that

$$\{\lambda_i Fr(y_i)\} \not\subseteq Q \text{ for each } i \in \{m, m + 1, \dots\}. \tag{3.14}$$

Let D be as in Theorem 3.6 and notice D is closed. We claim that D is compact. Indeed, let $\{x_n\}_1^\infty$ be any sequence in D . Then there exists a sequence $\{\lambda_n\}_1^\infty$ of $[0, 1]$ with $x_n \in \lambda_n Fr(x_n)$, $n = 0, 1, \dots$. We may assume, without loss of generality, that $\lambda_n \rightarrow \lambda \in [0, 1]$. Let $C = \{x_n\}_1^\infty$. Then C is countable with $C \subseteq \overline{co}(Fr(C) \cup \{0\})$. Consequently, if $\alpha(C) \neq 0$ then

$$\alpha(C) \leq \alpha(Fr(C)) < \alpha(r(C)) \leq \alpha(C), \text{ if } \alpha(r(C)) \neq 0,$$

whereas

$$\alpha(C) \leq \alpha(Fr(C)) \leq \alpha(r(C)) = 0 < \alpha(C), \text{ if } \alpha(r(C)) = 0.$$

This gives that $\alpha(C) = 0$ and so \overline{C} is compact. Consequently, there exists a subsequence N of $\{1, 2, \dots\}$ and a $x \in \overline{C}$ such that $x_n \rightarrow x$ as $n \rightarrow \infty$ in N . Since $x_n \in \lambda_n Fr(x_n)$, $n \in N$, by the closedness of F , we have $x \in \lambda Fr(x)$ and so $y \in D = \overline{D}$. Thus D is compact.

As a result we may assume without loss of generality that

$$\lambda_j \rightarrow \lambda^* \in [0, 1] \text{ and } y_j \rightarrow y^* \in \partial Q.$$

This implies $y^* \in \lambda^* Fr(y^*)$ with $0 \leq \lambda^* < 1$. This together with (3.12) implies $\{\lambda_j Fr(y_j)\} \subseteq Q$ for j sufficiently large. This contradicts (3.14) and so $B \cap Q \neq \emptyset$. Hence there exists $x \in Q$ with $x \in Fr(x) = F(x)$ ■

Theorem 3.7. *Let Q be a closed convex subset of a Hilbert space E with $0 \in Q$. Suppose $s : Q \rightarrow Q$ is surjective and $F \in s\text{-KKM}(Q, Q, E)$ is a closed, countably 1-set-contractive map with $F(Q)$ a bounded subset of E and assume (3.12) holds. In addition, suppose*

$$\begin{cases} \text{if } \{x_n\}_{j=1}^\infty \text{ is a sequence in } Q \text{ with } y_n \in F(x_n) \text{ for all } n \text{ and} \\ x_n - y_n \rightarrow 0 \text{ as } n \rightarrow \infty, \text{ then there exists } x \in Q \text{ with } x \in F(x). \end{cases} \tag{3.15}$$

Then F has a fixed point in Q .

Proof. For each $n \in \{2, 3, \dots\}$, let T_n be defined by

$$T_n(x) = \left(1 - \frac{1}{n}\right) F(x).$$

Consider the mapping $g_n(y) = \left(1 - \frac{1}{n}\right) y$. Then each g_n is continuous. Since $F \in s\text{-KKM}(Q, Q, E)$, we have $T_n = g_n F \in s\text{-KKM}(Q, Q, E)$ (by Remark 2.4). Since F is closed, each T_n is closed. Moreover, each T_n is countably condensing.

Let $\{(x_j, \lambda_j)\}_{j=1}^\infty$ be a sequence in $\partial C \times [0, 1]$ converging to (x, λ) with $x \in \lambda T_n(x)$ and $0 \leq \lambda < 1$. Then

$$\lambda_j T_n(x_j) = \lambda_j \left(1 - \frac{1}{n}\right) F(x_j) = \mu_j F(x_j),$$

for j sufficiently large, where $\mu_j = \lambda_j \left(1 - \frac{1}{n}\right)$ is a sequence in $[0, 1]$ with $\mu_j \rightarrow \lambda \left(1 - \frac{1}{n}\right) = \mu$, $0 \leq \mu < 1$, and $x \in \lambda T_n(x) = \mu F(x)$. By Theorem 3.6, each T_n has a fixed point $x_n \in Q$, i.e., $x_n \in \left(1 - \frac{1}{n}\right) F(x_n)$ for each n . Choose $y_n \in F(x_n)$ with $x_n = \left(1 - \frac{1}{n}\right) y_n$. It further implies that $x_n - y_n = -\frac{1}{n} y_n \rightarrow 0$ as $F(Q)$ is bounded. By (3.15), there exists an $x_0 \in Q$ with $x_0 \in F(x_0)$. ■

Next, we prove some Fan type approximation and fixed point theorems for S -KKM maps.

For $x \in E$, let

$$d_\mu(x, C) = \inf\{\mu(x - y) : y \in C\}.$$

Let $r : E \rightarrow C$ be defined by

$$r(x) = \begin{cases} x & \text{if } x \in C \\ \frac{x}{\mu(x)} & \text{if } x \notin C. \end{cases}$$

Theorem 3.8. *Let C be a closed, convex subset of a Banach space E with $0 \in \text{int}(C)$. Suppose $s : C \rightarrow C$ is surjective and $F \in s\text{-KKM}(C, C, E)$ is a closed map satisfying the following property:*

$$A \subseteq C, A \subseteq \overline{\text{co}}(\{0\} \cup F(\text{co}(\{0\} \cup A))) \text{ implies } \overline{A} \text{ is compact.}$$

Then there exist $x_0 \in C$ and y_0 such that $y_0 \in F(x_0)$ and

$$\mu(y_0 - x_0) = d_\mu(y_0, C) = d_\mu(y_0, \overline{I_C(x_0)});$$

here μ is the Minkowski functional of C in E . More precisely, either (i). F has a fixed point $x_0 \in C$, or (ii). there exist $x_0 \in \partial C$ and $y_0 \in F(x_0)$ with

$$0 < \mu(y_0 - x_0) = d_\mu(y_0, C) = d_\mu(y_0, \overline{I_C(x_0)}).$$

Proof. Let $r : E \rightarrow C$ be as defined above. Then r is continuous and

$$r(A) \subseteq \text{co}(A \cup \{0\})$$

for each bounded subset A of C . Let $G = Fr$. Essentially the same reasoning as in Theorem 3.1 guarantees that $G \in \mathbf{1}_E\text{-KKM}(E, E, E)$ is closed with

$$\text{if } A \subseteq E \text{ and } A \subseteq \text{co}(\{0\} \cup G(A)), \text{ then } \overline{A} \text{ is compact.}$$

Now Theorem 2.1 guarantees that there exists a $z_0 \in E$ such that $z_0 \in Fr(z_0)$. If we let $x_0 = r(z_0) \in C$, then $x_0 \in rF(x_0)$. Thus there exists some $y_0 \in F(x_0)$ such that $x_0 = r(y_0)$. Now we consider two cases: $y_0 \in C$ or $y_0 \notin C$.

If $y_0 \in C$, then $x_0 = r(y_0) = y_0$. Therefore

$$\mu(y_0 - x_0) = 0 = d_\mu(y_0, C)$$

and x_0 is a fixed point of F . On the other hand, if $y_0 \notin C$, then

$$x_0 = r(y_0) = \frac{y_0}{\mu(y_0)}.$$

As a result, for any $x \in C$,

$$\begin{aligned} \mu(y_0 - x_0) &= \mu\left(y_0 - \frac{y_0}{\mu(y_0)}\right) = \left(\frac{\mu(y_0) - 1}{\mu(y_0)}\right)\mu(y_0) \\ &= \mu(y_0) - 1 \leq \mu(y_0 - x). \end{aligned}$$

Consequently $\mu(y_0 - x_0) \leq d_\mu(y_0, C)$ and so $\mu(y_0 - x_0) = d_\mu(y_0, C)$. Moreover, $\mu(y_0 - x_0) > 0$ since $\mu(y_0 - x_0) = \mu(y_0) - 1$.

It remains to show $\mu(y_0 - x_0) = d_\mu(y_0, \overline{I_C(x_0)})$. Let $z \in I_C(x_0) \setminus C$. Then there exists $y \in C$ and $c \geq 1$ with $z = x_0 + c(y - x_0)$. Suppose that

$$\mu(y_0 - z) < \mu(y_0 - x_0).$$

The convexity of C implies that $\frac{1}{c}z + (1 - \frac{1}{c})x_0 \in C$. Now

$$\begin{aligned} \mu(y_0 - y) &= \mu\left[\frac{1}{c}(y_0 - z) + \left(1 - \frac{1}{c}\right)(y_0 - x_0)\right] \\ &\leq \frac{1}{c}\mu(y_0 - z) + \left(1 - \frac{1}{c}\right)\mu(y_0 - x_0) \\ &< \mu(y_0 - x_0). \end{aligned}$$

This contradicts the choice of y_0 . Thus we have

$$\mu(y_0 - x_0) \leq \mu(y_0 - z) \text{ for all } z \in I_C(x_0).$$

Since μ is continuous, we have

$$\mu(y_0 - x_0) \leq \mu(y_0 - z) \text{ for all } z \in \overline{I_C(x_0)}.$$

Hence

$$0 < \mu(y_0 - x_0) = d_\mu(y_0, C) = d_\mu(y_0, \overline{I_C(x_0)}).$$

Suppose $x_0 \in \text{int}(C)$. Then $\overline{I_C(x_0)} = E$, which implies $d_\mu(y_0, \overline{I_C(x_0)}) = 0$. This shows that $x_0 \in \partial C$. ■

Essentially the same reasoning as in Theorem 3.8 (except here we use Theorem 2.2) establishes the following result.

Theorem 3.9. *Let C be a closed, convex subset of a Banach space E with $0 \in \text{int}(C)$. Suppose $s : C \rightarrow C$ is surjective and $F \in s\text{-KKM}(C, C, E)$ is a closed map satisfying the following properties:*

$$A \subseteq C, A \subseteq \text{co}(\{0\} \cup F(\text{co}(\{0\} \cup A))) \text{ implies } \overline{A} \text{ is compact}$$

and

$$F(\overline{A}) \subseteq \overline{F(A)} \text{ for any relatively compact subset } A \text{ of } C.$$

Then there exist $x_0 \in C$ and y_0 such that $y_0 \in F(x_0)$ and

$$\mu(y_0 - x_0) = d_\mu(y_0, C) = d_\mu(y_0, \overline{I_C(x_0)}),$$

here μ is the Minkowski functional of C in E . More precisely, either (i) F has a fixed point $x_0 \in C$, or (ii) there exist $x_0 \in \partial C$ and $y_0 \in F(x_0)$ with

$$0 < \mu(y_0 - x_0) = d_\mu(y_0, C) = d_\mu(y_0, \overline{I_C(x_0)}).$$

Essentially the same arguments as in Theorem 3.8 (except here we use Theorem 2.3) yields the following result.

Theorem 3.10. *Let C be a closed, convex subset of a Banach space E with $0 \in \text{int}(C)$. Suppose $s : C \rightarrow C$ is surjective and $F \in s\text{-KKM}(C, C, E)$ is a closed map satisfying the following properties:*

$$\begin{cases} A \subseteq C, A \subseteq \text{co}(\{0\} \cup F(\text{co}(\{0\} \cup A))) \text{ with } \overline{A} = \overline{Q} \\ \text{and } Q \subseteq A \text{ countable, implies } \overline{A} \text{ is compact,} \\ F(\overline{A}) \subseteq \overline{F(A)} \text{ for any relatively compact subset } A \text{ of } C, \\ \begin{cases} \text{for any relatively compact subset } A \text{ of } C, \text{ there} \\ \text{exists a countable set } B \subseteq A \text{ with } \overline{B} = \overline{A}, \end{cases} \end{cases}$$

and

if A is a compact subset of C , then $\overline{\text{co}}(A)$ is compact.

Then there exist $x_0 \in C$ and y_0 such that $y_0 \in F(x_0)$ and

$$\mu(y_0 - x_0) = d_\mu(y_0, C) = d_\mu(y_0, \overline{I_C(x_0)});$$

here μ is the Minkowski functional of C in E . More precisely, either (i) F has a fixed point $x_0 \in C$, or (ii) there exist $x_0 \in \partial C$ and $y_0 \in F(x_0)$ with

$$0 < \mu(y_0 - x_0) = d_\mu(y_0, C) = d_\mu(y_0, \overline{I_C(x_0)}).$$

Using Theorem 2.4 and following the arguments above, we obtain the following results.

Theorem 3.11. *Let C be a closed, convex subset of a Banach space E with $0 \in \text{int}(C)$. Suppose $s : C \rightarrow C$ is surjective and $F \in s\text{-KKM}(C, C, E)$ is a closed, countably condensing map. Then there exist $x_0 \in C$ and y_0 such that $y_0 \in F(x_0)$ and*

$$\mu(y_0 - x_0) = d_\mu(y_0, C) = d_\mu(y_0, \overline{I_C(x_0)});$$

here μ is the Minkowski functional of C in E . More precisely, either (i) F has a fixed point $x_0 \in C$, or (ii) there exist $x_0 \in \partial C$ and $y_0 \in F(x_0)$ with

$$0 < \mu(y_0 - x_0) = d_\mu(y_0, C) = d_\mu(y_0, \overline{I_C(x_0)}).$$

In the case when E is a Hilbert space, we have the following result. For details, we refer the reader to [13, 14, 17]. Note that, in this case, the mapping r is replaced by the nearest point projection.

Theorem 3.12. *Let C be a closed, convex subset of a Hilbert space E . Suppose $s : C \rightarrow C$ is surjective and $F \in s\text{-KKM}(C, C, E)$ is a closed, countably condensing map. Then there exist x_0 and y_0 such that $y_0 \in F(x_0)$ and*

$$\|y_0 - x_0\| = d(y_0, C) = d(y_0, \overline{I_C(x_0)});$$

here $\|\cdot\|$ is the norm induced by the inner product. More precisely, either (i) F has a fixed point $x_0 \in C$, or (ii) there exist $x_0 \in \partial C$ and $y_0 \in F(x_0)$ with

$$0 < \|y_0 - x_0\| = d(y_0, C) = d(y_0, \overline{I_C(x_0)}).$$

Using these approximation results, we now prove some fixed point theorems.

Theorem 3.13. *Let C be a closed, convex subset of a Banach space E with $0 \in \text{int}(C)$. Suppose $s : C \rightarrow C$ is surjective and $F \in s\text{-KKM}(C, C, E)$ is a closed map satisfying the following property:*

$$A \subseteq C, A \subseteq \overline{\text{co}(\{0\} \cup F(\text{co}(\{0\} \cup A)))} \text{ implies } \overline{A} \text{ is compact} \quad (H)$$

If F satisfies any one of the following conditions for any $x \in \partial C \setminus F(x)$:

- (i) For each $y \in F(x)$, $\mu(y - z) < \mu(y - x)$ for some $z \in \overline{I_C(x)}$;
 - (ii) For each $y \in F(x)$, there exists λ with $|\lambda| < 1$ such that $\lambda x + (1 - \lambda)y \in \overline{I_C(x)}$;
 - (iii) $F(x) \subseteq \overline{I_C(x)}$;
 - (iv) For each $\lambda \in (0, 1)$, $x \notin \lambda F(x)$;
 - (v) For each $y \in F(x)$, $\mu(y - x) \neq \mu(y) - 1$;
 - (vi) For each $y \in F(x)$, there exists $\alpha \in (1, \infty)$ such that $\mu^\alpha(y) - 1 \leq \mu^\alpha(y - x)$;
 - (vii) For each $y \in F(x)$, there exists $\beta \in (0, 1)$ such that $\mu^\beta(y) - 1 \geq \mu^\beta(y - x)$,
- then F has a fixed point.

Proof. By Theorem 3.8, either

- (1) F has a fixed point in C

or

- (2) there exist $x_0 \in \partial C$ and $y_0 \in F(x_0)$ with $x_0 = r(y_0)$ such that

$$0 < \mu(y_0) - 1 = \mu(y_0 - x_0) = d_\mu(y_0, C) = d_\mu(y_0, \overline{I_C(x_0)}),$$

where μ is the Minkowski functional of C in E .

Suppose F satisfies condition (i). Assume (2) holds (with x_0 and y_0 as described above) and $x_0 \notin \overline{F(x_0)}$. Then, by condition (i), we have $\mu(y_0 - z) < \mu(y_0 - x_0)$ for some $z \in \overline{I_C(x_0)}$. This contradicts $\mu(y_0 - x_0) = d_\mu(y_0, \overline{I_C(x_0)})$. Hence F has a fixed point in C .

Suppose F satisfies condition (ii). Assume (2) holds (with x_0 and y_0 as described above) and $x_0 \notin \overline{F(x_0)}$. Then, by condition (ii), there exists λ with $|\lambda| < 1$ such that $\lambda x_0 + (1 - \lambda)y_0 \in \overline{I_C(x_0)}$. This implies that

$$\begin{aligned} \mu(y_0 - x_0) &\leq \mu(y_0 - (\lambda x_0 + (1 - \lambda)y_0)) \\ &< \mu(y_0 - x_0), \end{aligned}$$

which is impossible. Hence F has a fixed point in C .

The proof for condition (iii) is obvious.

Suppose F satisfies condition (iv). Assume (2) holds (with x_0 and y_0 as described above) and $x_0 \notin F(x_0)$. Then, by condition (iv), $x_0 \notin \lambda F(x_0)$ for each $\lambda \in (0, 1)$. This implies that $x_0 \neq \lambda y_0$ for each $\lambda \in (0, 1)$. But we have $x_0 = \frac{y_0}{\mu(y_0)}$ with $\mu(y_0) > 1$. Hence F has a fixed point in C .

Suppose F satisfies condition (v). Assume (2) holds (with x_0 and y_0 as described above) and $x_0 \notin F(x_0)$. Then, by condition (v), $\mu(y_0 - x_0) \neq \mu(y_0) - 1$. But we have $\mu(y_0 - x_0) = \mu(y_0) - 1$. Hence F has a fixed point in C .

Suppose F satisfies condition (vi). Assume (2) holds (with x_0 and y_0 as described above) and $x_0 \notin F(x_0)$. Then, by condition (vi), there exists $\alpha \in (1, \infty)$ with $\mu^\alpha(y_0) - 1 \leq \mu^\alpha(y_0 - x_0)$. Let $\lambda_0 = \frac{1}{\mu(y_0)}$. Then $\lambda_0 \in (0, 1)$ and

$$\frac{(\mu(y_0) - 1)^\alpha}{\mu^\alpha(y_0)} < 1 - \lambda_0^\alpha \leq \frac{\mu^\alpha(y_0 - x_0)}{\mu^\alpha(y_0)}.$$

Thus $\mu(y_0 - x_0) > \mu(y_0) - 1$. This contradicts $\mu(y_0 - x_0) = \mu(y_0) - 1$. Hence F has a fixed point in C .

Finally suppose F satisfies condition (vii). Then, as above (see the proof of (vi)), it can be shown that F has a fixed point in C . ■

Remark 3.2. Essentially the same reasoning as in Theorem 3.13 shows that the conclusion remains true if condition (H) is replaced by any one of the following conditions:

$$A \subseteq C, A \subseteq \text{co}(\{0\} \cup F(\text{co}(\{0\} \cup A))) \text{ implies } \overline{A} \text{ is compact} \tag{H1}$$

and

$$\begin{aligned} &F(\overline{A}) \subseteq \overline{F(A)} \text{ for any relatively compact subset } A \text{ of } C, \\ &\left\{ \begin{array}{l} A \subseteq C, A \subseteq \text{co}(\{0\} \cup F(\text{co}(\{0\} \cup A))) \text{ with } \overline{A} = \overline{Q} \\ \text{and } Q \subseteq A \text{ countable, implies } \overline{A} \text{ is compact,} \end{array} \right. \tag{H2} \\ &F(\overline{A}) \subseteq \overline{F(A)} \text{ for any relatively compact subset } A \text{ of } C, \\ &\left\{ \begin{array}{l} \text{for any relatively compact subset } A \text{ of } C, \text{ there} \\ \text{exists a countable set } B \subseteq A \text{ with } \overline{B} = \overline{A}, \end{array} \right. \end{aligned}$$

and

if A is a compact subset of C , then $\overline{\text{co}}(A)$ is compact.

$$F \text{ is countably condensing.} \tag{H3}$$

Theorem 3.14. *Let C be a closed, convex subset of a Hilbert space E . Suppose $s : C \rightarrow C$ is surjective and $F \in s\text{-KKM}(C, C, E)$ is a closed, countably condensing map. If F satisfies any one of the following conditions for any $x \in \partial C \setminus F(x)$:*

- (i) *For each $y \in F(x)$, $\|y - z\| < \|y - x\|$ for some $z \in \overline{I_C(x)}$;*
- (ii) *For each $y \in F(x)$, there exists λ with $|\lambda| < 1$ such that $\lambda x + (1 - \lambda)y \in \overline{I_C(x)}$;*
- (iii) *$F(x) \subseteq \overline{I_C(x)}$.*

Then F has a fixed point.

Remark 3.3. For $R > 0$, let $B_R = \{x \in E : \|x\| \leq R\}$. Then $\mu(\cdot) = \frac{\|\cdot\|}{R}$ is the Minkowski functional of B_R in E . One can easily obtain results using Theorems 3.8–3.11 and Theorem 3.13 in the case when C is replaced by B_R . For details, we refer the reader to [13, 14, 17].

Acknowledgement. The authors are grateful to the referee for his/her suggestions and careful reading of the manuscript.

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