

Basic Analogue of I -Function of Several Matrix Arguments

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Abstract. In the present paper the authors define a new basic analogue of I -function of several matrix arguments. As $q \rightarrow 1^-$, it reduces to the Lauricella functions studied by Mathai. Two integral relations for this function, multiplication formula, convolution for the M -transform for the function of several matrix arguments and application to integral equation are investigated.

1. Introduction

The H -function of matrix arguments is defined as follows [9, 10]

$$\int_{Z>0} (\det Z)^{\rho - \frac{m+1}{2}} H(Z, p, \bar{n}, \bar{a}, \bar{\alpha}) dZ = X_{\bar{n}, \bar{a}, \bar{\alpha}}^p(\rho),$$

where

$$X_{\bar{n}, \bar{a}, \bar{\alpha}}^p(\rho) = \prod_{i=1}^p \Gamma_m^{n_i}(A_i + \alpha_i \rho),$$

$$A_i = \frac{m+1}{4} + \left(a_i - \frac{m+1}{4}\right) \text{sign}(\alpha_i),$$

$\Gamma_m(\delta)$ is the generalized gamma - function,
 p is a natural number, ρ is a complex number,
 $\bar{n} = (n_1, n_2, \dots, n_p)$, n_i are integers,
 $\bar{a} = (a_1, a_2, \dots, a_p)$, a_i are complex numbers,
 $\bar{\alpha} = (\alpha_1, \alpha_2, \dots, \alpha_p)$, α_i are real numbers,

$\operatorname{Re}(A_i + \alpha_i \rho) > \frac{m-1}{2} \alpha_i, i = 1, \dots, p.$

$Z > 0$ means that Z is a $m \times m$ real symmetric positive definite matrix,
 $dZ = \prod_{i \geq j} dx_{ij}.$

All gamma - functions are assumed to exist, the poles of the functions $X_{n, \underline{a}, \overline{\alpha}}^p(\rho), \alpha_i > 0, n_i > 0, i = 1, \dots, p,$ and those of $X_{n, \underline{a}, \overline{\alpha}}^p(\rho), \alpha_i < 0, n_i > 0, i = 1, \dots, p,$ are assumed to be separated from each other.

The special cases of H -function with matrix argument are known as H -function (see Fox [2]), G -function (Meijer [2]).

In 1995, Mathai studied some functions of several matrix arguments: Lauricella functions [7], Φ_2 and ψ_2 -functions, Humbert's functions [8], Appell's and Kampe-de-Feriet's functions [8].

Let us consider the integral transform $K : U(X) \rightarrow V(Y)$, where $U(X)$ is a linear space, $V(Y)$ is an algebraic one. The convolution of two functions f, g for the transform K is defined by the symbol $f * g$, such that the following factorization property is valid:

$$K(f * g)(y) = (Kf)(y)(Kg)(y), \quad y \in Y.$$

In 1942, for the first time Churchill initiated the convolution of functions f, g for the Fourier transform in the famous form as follows [1]:

$$(f * g)(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{+\infty} f(x-t)g(t)dt.$$

Later on, convolutions for the Mellin, Laplace, cosine-Fourier, Hilbert, Stieltjes and I -transform have been investigated [4, 15-17]:

$$\begin{aligned} (f * g)(x) &= \int_0^{+\infty} f\left(\frac{x}{t}\right)g(t)\frac{dt}{t}, \\ (f * g)(x) &= \int_0^x f(x-t)g(t)dt, \\ (f * g)(x) &= \frac{1}{\sqrt{2\pi}} \int_0^{+\infty} [f(|x-t|) + f(x+t)]g(t)dt, \\ (f * g)(x) &= \frac{1}{\pi} \int_{-\infty}^{+\infty} \frac{f(x)g(t) + f(t)g(x) + f(t)g(t)}{x-t} dt, \\ (f * g)(x) &= f(x) \int_0^{+\infty} \frac{g(t)dt}{t-x} + g(x) \int_0^{+\infty} \frac{f(t)}{t-x} dt. \end{aligned}$$

In the present paper, we will assume the basic analogue of I -function of several matrix arguments, including, for example, Lauricella function [8], hypergeometric function [8], Fox's H -function [1]. Integral relation, contiguous

correlations, convolution for M -transform and its application to integral equations are established.

2. I-Function of Several Matrix Arguments

Definition 1. A basic analogue of I-function of several matrix arguments is defined as follows:

$$\int_{Z^N > 0} (\det Z)^{\rho - \frac{m+1}{2}} I_q(Z | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i) dZ = \Theta(\rho), \tag{1}$$

where

$$\frac{1}{\Theta(\rho)} = \sum_{i=1}^r Q_{\bar{n}_i, \bar{a}_i, \alpha_i}^{p_i}(\rho) \neq 0,$$

$$Q_{\bar{n}_i, \bar{a}_i, \alpha_i}^{p_i}(\rho) = \pi^{\frac{m}{2}(m-1)} \sum_{j=1}^p n_{ij} \prod_{j=1}^p \prod_{t=1}^m \Gamma_{q,m}^{n_{ij}} \left(a_{ij} - \frac{t-1}{2} + \sum_{k=1}^N \alpha_{ijk} \rho_k \right),$$

$\Gamma_{q,m}(\delta)$ is a product of the q -gamma functions [5]:

$$\Gamma_{q,m}(\delta) = \pi^{\frac{m(m-1)}{4}} \Gamma_q\left(\delta - \frac{1}{2}\right) \dots \Gamma_q\left(\delta - \frac{m-1}{2}\right),$$

$$\Gamma_q(s) = \frac{(q, q)_{\infty}}{(q^s, q)_{\infty}} (1-q)^{1-s}, \quad (a; q)_{\infty} = \prod_{n=0}^{\infty} (1-aq^n), \quad |q| < 1$$

r, p_i, m, N are natural numbers, ρ_j are complex numbers,
 $\bar{n}_i = (n_{i1}, n_{i2}, \dots, n_{ip_i}), n_{ij}$ are integers,
 $\bar{a}_i = (a_{i1}, a_{i2}, \dots, a_{ip_i}), a_{ij}$ are complex numbers,
 $\alpha_i = (\alpha_{ijk})_{p_i \times N}, \alpha_{ijk}$ are real numbers, $i = 1, \dots, r, j = 1, \dots, p_i, k = 1, \dots, N,$

$$Z = (Z_1, \dots, Z_N), (\det Z)^{\rho - \frac{m+1}{2}} = \prod_{k=1}^N (\det Z_k)^{\rho_k - \frac{m+1}{2}},$$

$\{Z^N > 0\} = \{Z_k > 0, k = 1, \dots, N\}, Z_k > 0$ means that Z_k is an $m \times m$ real symmetric positive definite matrix.

$$dZ = \prod_{k=1}^N dZ_k, \quad \operatorname{Re}\left(a_{ij} + \sum_{k=1}^N \alpha_{ijk} \rho_k\right) > \frac{m-1}{2}, \quad i = 1, \dots, r, \quad j = 1, \dots, p_i.$$

All gamma-functions are assumed to exist, the poles of function $\Theta(\rho), \alpha_{ijk} > 0, n_{ij} > 0, i = 1, \dots, r, j = 1, \dots, p_i, k = 1, \dots, N,$ and those of $\Theta(\rho), \alpha_{ijk} < 0, n_{ij} > 0, i = 1, \dots, r, j = 1, \dots, p_i, k = 1, \dots, N,$ are assumed to be separated from each other.

Remark. Basic analogue of I-functions (1) is very general, and with certain constraints on the parameters of them we arrive at well-known functions. For

examples, when $N = 1, m = 1$, we have a basic analogue of I -functions [13], when $N = 2, m = 1$, we obtain that of I -functions of two variables [11], when $N = 1, m = 1, r = 1$, we have a basic analogue of Fox' H -functions [14], when $N = 2, m = 1, r = 1$, we obtain that of H -functions of two variables [6], and when $m = 1, r = 1$, we have that of H -functions of several variables [12].

Theorem 1. a) *If*

$$\begin{aligned} r = 1, \quad p = 5N + 2, \quad n_1 = 1, \quad a_1 = a, \alpha_{1j} = 0, \\ n_2 = -1, \quad a_2 = \frac{m+1}{2} - a, \quad \alpha_{2j} = -1, \\ n_{2+i} = 1, \quad a_{2+i} = \frac{m+1}{2} - b_i, \quad \alpha_{2+i,j} = 0, \\ n_{2+N+i} = -1, \quad a_{2+N+i} = b_i, \quad \alpha_{2+N+i,j} = \begin{cases} -1 & j = i \\ 0 & j \neq i \end{cases}, \\ n_{2+2N+i} = -1, \quad a_{2+2N+i} = c_i, \quad \alpha_{2+2N+i,j} = 0, \\ n_{2+3N+i} = 1, \quad a_{2+3N+i} = \frac{m+1}{2} - c_i, \quad \alpha_{2+3N+i,j} = \begin{cases} -1 & j = i \\ 0 & j \neq i \end{cases}, \\ n_{2+4N+i} = -1, \quad a_{2+4N+i} = 0, \quad \alpha_{2+4N+i,j} = \begin{cases} 1 & j = i \\ 0 & j \neq i \end{cases}, \end{aligned}$$

then the following statement holds

$$\lim_{q \rightarrow 1^-} I_q(Z | 1, p, \bar{n}, \bar{a}, \alpha) = f_A(a, b_1, \dots, b_N; c_1, \dots, c_N; -Z_1, \dots, -Z_N),$$

where $f_A(\cdot)$ and $f_B(\cdot), f_C(\cdot), f_D(\cdot)$ are Lauricella functions [7].

b) *If*

$$\begin{aligned} r = 1, \quad p = 5N + 2, \quad n_i = 1, \quad \alpha_{ij} = 0, \\ n_{N+i} = -1, \quad a_{N+i} = \frac{m+1}{2} - a_i, \quad \alpha_{N+i,j} = \begin{cases} -1 & j = i \\ 0 & j \neq i \end{cases}, \\ n_{2N+i} = 1, \quad a_{2N} = b_i, \quad \alpha_{2N+i,j} = 0, \\ n_{3N+i} = -1, \quad a_{3N+i} = \frac{m+1}{2} - b_i, \quad \alpha_{3N+i,j} = \begin{cases} -1 & j = i \\ 0 & j \neq i \end{cases}, \\ n_{4N+1} = -1, \quad a_{4N+1} = c, \quad \alpha_{4N+1,j} = 0, \\ n_{4N+2} = -1, \quad a_{4N+2} = \frac{m+1}{2} - c; \quad \alpha_{4N+2,j} = -1, \\ n_{4N+2+i} = -1, \quad a_{4N+2+i} = 0, \quad \alpha_{4N+2+i,j} = \begin{cases} -1 & j = i \\ 0 & j \neq i \end{cases}, \end{aligned}$$

then

$$\lim_{q \rightarrow 1^-} I_q(Z | 1, p, \bar{n}, \bar{a}, \alpha) = f_B(a_1, \dots, a_N; b_1, \dots, b_N; c; -Z_1, \dots, -Z_N).$$

c) If

$$\begin{aligned}
 r &= 1 \quad p = 3N + 4, \quad n_1 = 1, \quad a_1 = a, \quad \alpha_1 = 0, \\
 n_2 &= -1, \quad a_2 = \frac{m+1}{2} - a, \quad \alpha_{2j} = -1, \\
 n_3 &= 1, \quad a_3 = b, \quad \alpha_{3j} = 0 \\
 n_4 &= -1, \quad a_4 = \frac{m+1}{2} - b, \quad \alpha_{4j} = -1, \\
 n_{4+i} &= -1, \quad a_{4+i} = c_i, \quad \alpha_{4+i,j} = 0, \\
 n_{N+4+i} &= 1, \quad a_{N+4+i} = \frac{m+1}{2} - c_i, \quad \alpha_{N+4+i,j} = \begin{cases} -1 & j = i \\ 0 & j \neq i \end{cases}, \\
 n_{2N+4+i} &= -1, \quad a_{2N+4+i} = 0, \quad \alpha_{2N+4+i,j} = \begin{cases} -1 & j = i \\ 0 & j \neq i \end{cases},
 \end{aligned}$$

then

$$\lim_{q \rightarrow 1^-} I_q(Z|1, p, \bar{n}, \bar{a}_1, \alpha) = f_C(a, b; c_1, \dots, c_N; -Z_1, \dots, -Z_N).$$

d) If

$$\begin{aligned}
 r &= 1 \quad p = 3N + 4, \quad n_1 = 1, \quad a_1 = a, \quad \alpha_{1j} = 0, \\
 n_2 &= -1, \quad a_2 = \frac{m+1}{2} - a, \quad \alpha_{2j} = -1, \\
 n_{2+i} &= 1, \quad a_{2+i} = b_i, \quad \alpha_{2+i,j} = 0, \\
 n_{N+2+i} &= -1, \quad a_{N+2+i} = \frac{m+1}{2} - b_i, \quad \alpha_{N+2+i,j} = \begin{cases} -1 & j = i \\ 0 & j \neq i \end{cases}, \\
 n_{2N+3} &= -1, \quad a_{2N+3} = c, \quad \alpha_{2N+3,j} = 0, \\
 n_{2N+4} &= 1, \quad a_{2N+4} = \frac{m+1}{2} - c, \quad \alpha_{2N+4,j} = -1, \\
 n_{2N+4+i} &= -1, \quad a_{2N+4+i} = 0 \quad \alpha_{2N+4+i,j} = \begin{cases} 1 & j = i \\ 0 & j \neq i \end{cases},
 \end{aligned}$$

then the following statement holds

$$\lim_{q \rightarrow 1^-} I_q(Z|1, p, \bar{n}, \bar{a}, \alpha) = f_D(a, b_1, \dots, b_N; c; -Z_1, \dots, -Z_N).$$

Consequence 1.

a) If

$$\begin{aligned}
 r &= 1 \quad p = 3N + 2, \quad n_1 = 1, \quad a_1 = a, \quad \alpha_{1j} = 0, \\
 n_2 &= -1, \quad a_2 = \frac{m+1}{2} - a, \quad \alpha_{2j} = -1, \\
 n_{2+i} &= -1, \quad a_{2+i} = c_i, \quad \alpha_{2+i,j} = 0, \\
 n_{2+N+i} &= 1, \quad a_{2+N+i} = \frac{m+1}{2} - c_i, \quad \alpha_{2+N+i,j} = \begin{cases} -1 & j = i \\ 0 & j \neq i \end{cases}, \\
 n_{2+2N+i} &= -1, \quad a_{2+2N+i} = 0, \quad \alpha_{2+2N+i,j} = \begin{cases} -1 & j = i \\ 0 & j \neq i \end{cases}, \quad i, j = 1, \dots, N,
 \end{aligned}$$

then

$$\lim_{q \rightarrow 1^-} I_q(Z|1, p, \bar{n}, \bar{a}, \alpha) = \psi_2(a; c_1, \dots, c_N; -Z_1, \dots, -Z_N).$$

b) If

$$\begin{aligned} r &= 1, \quad p = 3N + 2, \quad n_i = 1, \quad a_i = b_i, \quad \alpha_{ij} = 0, \\ n_{N+i} &= -1, \quad a_{N+i} = \frac{m+1}{2} - b_i, \quad \alpha_{N+i,j} = \begin{cases} -1 & j = i \\ 0 & j \neq i \end{cases}, \\ n_{2N+1} &= -1, \quad a_{2N+1} = c, \quad \alpha_{2N+1,j} = 0, \\ n_{2N+2} &= 1, \quad a_{2N+2} = \frac{m+1}{2} - c, \quad \alpha_{2N+2,j} = -1, \\ n_{2+2N+i} &= -1, \quad a_{2+2N+i} = 0, \quad \alpha_{2+2N+i,j} = \begin{cases} 1 & j = i \\ 0 & j \neq i \end{cases}, \quad i, j = 1, \dots, N, \end{aligned}$$

then the following statement holds valid

$$\lim_{q \rightarrow 1^-} I_q(Z|1, p, \bar{n}, \bar{a}, \alpha) = \phi_2(b_1, \dots, b_N; c; -Z_1, \dots, -Z_N),$$

where functions ψ_2, ϕ_2 are defined in [8].

Consequence 2. If

$$\begin{aligned} r' &= 1, \quad p = N + 2s + 2r, \quad n_i = 1, \quad \alpha_{ij} = 0, \\ n_{r+i} &= -1, \quad a_{r+i} = a_i, \quad \alpha_{r+i,j} = 1, \quad i = 1, \dots, r, \\ n_{2r+k} &= -1, \quad a_{2r+k} = b_k, \quad \alpha_{2r+k,j} = 0, \\ n_{2r+s+k} &= 1, \quad a_{2r+s+k} = b_k, \quad \alpha_{2r+s+k,j} = -1, \quad k = 1, \dots, s, \\ n_{2r+2s+t} &= -1, \quad a_{2r+2s+t} = 0, \quad \alpha_{2r+2s+t,j} = \begin{cases} 1 & t = j \\ 0 & t \neq j \end{cases}, \quad t, j = 1, \dots, N, \end{aligned}$$

then

$$\lim_{q \rightarrow 1^-} I_q(Z|1, p, \bar{n}, \bar{a}, \alpha) = {}_rF_s(a_1, \dots, a_r; b_1, \dots, b_s; -Z_1, \dots, -Z_N),$$

where the hypergeometric function ${}_rF_s$ is defined in [8].

Under supplemental conditions, the basic analogue of I -function of two matrix argument will coincide, for example, Humbert's function [8], Kampe de Fariet's function [8], Appell's function [8].

Theorem 2. *If $Z_i, A_i, i = 1, \dots, N$, are $m \times m$ symmetric matrices, then the following formula is true:*

$$\begin{aligned} &\int_{Z^N > 0} (\det Z)^{\rho - \frac{m+1}{2}} I_q(ZA|r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i) I_q(Z|s, q_j, \bar{t}_j, \bar{b}_j, \beta_j) dZ = \\ &= I_q\left(A|r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i; s, q_j, \bar{t}_j, \bar{b}_j + \sum_{k=1}^N \left(\rho_k - \frac{m-1}{2}\right) \bar{\beta}_{jk}, \beta_j\right), \end{aligned}$$

where $\bar{\beta}_j = (\beta_{1j}, \dots, \beta_{pj})$.

Proof. From (1) it follows that

$$\int_{A^N > 0} (\det A)^{\rho - \frac{m+1}{2}} I_q(ZA | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i) dA = (\det Z)^{-\rho - \frac{m-1}{2}} \left(\sum_{i=1}^r Q_{\bar{n}_i, \bar{a}_i, \alpha_i}^{p_i}(\rho) \right)^{-1}.$$

Then we have

$$\begin{aligned} & \int_{A^N > 0} (\det A)^{\eta - \frac{m+1}{2}} \\ & \times \left\{ \int_{Z^N > 0} (\det Z)^{\rho - \frac{m+1}{2}} I_q(ZA | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i) I_q(Z | s, q_j, \bar{t}_j, \bar{b}_j, \beta_j) dZ \right\} dA \\ & = \int_{Z^N > 0} (\det Z)^{\rho - \frac{m+1}{2}} I_q(Z | s, q_j, \bar{t}_j, \bar{b}_j, \beta_j) \\ & \times \left\{ \int_{A^N > 0} (\det A)^{\eta - \frac{m+1}{2}} I_q(ZA | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i) dA \right\} dZ \\ & = \left(\sum_{i=1}^r Q_{\bar{n}_i, \bar{a}_i, \alpha_i}^{p_i}(\eta) \right)^{-1} \\ & \times \int_{Z^N > 0} (\det Z)^{(\rho - \eta - \frac{m-1}{2}) - \frac{m+1}{2}} I_q(Z | s, q_j, \bar{t}_j, \bar{b}_j, \beta_j) dZ \\ & = \left(\sum_{i=1}^r Q_{\bar{n}_i, \bar{a}_i, \alpha_i}^{p_i}(\eta) \right)^{-1} \left(\sum_{j=1}^s Q_{\bar{t}_j, \bar{b}_j, \beta_j}^{q_j} \left(\rho - \eta - \frac{m-1}{2} \right) \right)^{-1} \\ & = \left(\sum_{i,j=1}^{r,s} Q_{\bar{n}_i, \bar{a}_i, \alpha_i}^{p_i}(\eta) Q_{\bar{t}_j, \bar{b}_j, \beta_j}^{q_j} \left(\rho - \eta - \frac{m-1}{2} \right) \right)^{-1}. \end{aligned}$$

Thus, Theorem 2 is proved. ■

Theorem 3. *The following formulas are true:*

a)

$$\begin{aligned} & A \int_{[0,1]^m} \prod_{j=1}^m x_j^{\sigma - \frac{j+1}{2}} E_q(qx_j) I_q((x_1 \dots x_m)^{-\delta} Z | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i) d_q x_1 \dots d_q x_m \\ & = I_q \left((1-q)^{-m\delta} Z | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i; 1, -1, \sigma + \frac{1-m}{2} \sum_{j=1}^N \delta_j, \delta \right), \end{aligned}$$

where $E_q(x)$ is an exponential function, $\int_0^1 f(x) d_q x$ is q -integral [3],

$$\begin{aligned} \operatorname{Re} \sigma > 0, \quad \delta_j > 0, \quad \delta = (\delta_1, \dots, \delta_N), \\ (x_1 \dots x_m)^{-\delta} Z = ((x_1 \dots x_m)^{-\delta_1} Z_1, \dots, (x_1 \dots x_m)^{-\delta_N} Z_N), \end{aligned}$$

$$A = \pi^{\frac{m}{4}(m-1)} (1-q)^{-m\sigma - \frac{m(m-1)}{4} + \frac{m}{2}(m-1) \sum_{k=1}^N \delta_k}.$$

b)

$$\begin{aligned} B & \int_{[0,1]^m} \prod_{j=1}^m x_j^{\sigma - \frac{j+1}{2}} (1-qx_j)^{\delta - \sigma - 1} \\ & \times I_q((x_1 \dots x_m)^{-\gamma} Z | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i) d_q x_1 \dots d_q x_m \\ & = I_q\left(Z | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i; 1, -1, \sigma + \frac{1-m}{2} \sum_{j=1}^N \gamma_j, \gamma; 1, 1, \delta + \frac{1-m}{2} \sum_{j=1}^N \gamma_j, \gamma\right), \end{aligned}$$

where

$$\begin{aligned} \operatorname{Re} \sigma > 0, \quad \operatorname{Re} \delta_j > 0, \quad \operatorname{Re}(\delta - \sigma) > 0, \quad \gamma_j > 0, \\ (1-y)_\beta = \prod_{n=0}^{\infty} (1-yq^n)(1-yq^{n+\beta})^{-1}, \quad B = \Gamma_q^{-m}(\delta - \sigma). \end{aligned}$$

Proof. Utilize formulas of ([5, p. 372]):

$$\begin{aligned} \frac{G(q)}{1-q} \int_0^1 t^{\beta-s-1} E_q(qt) d_q t &= G(q^{\beta-s}), \\ G(q^\alpha) &= \prod_{n=0}^{\infty} (1-q^{\alpha+n})^{-1}, \\ \frac{1}{1-q} \int_0^1 t^{\alpha-1} (1-qt)_{\beta-1} d_q t &= \prod_{n=0}^{\infty} \frac{(1-q^{\alpha+\beta+n})(1-q^{1+n})}{(1-q^{\alpha+n})(1-q^{\beta+n})}, \end{aligned}$$

we have

$$\begin{aligned} & \int_{Z^N > 0} (\det Z)^{\rho - \frac{m+1}{2}} \times \left\{ \int_{[0,1]^m} \prod_{j=1}^m x_j^{\sigma - \frac{j+1}{2}} (1-qx_j)^{\delta - \sigma - 1} \times \right. \\ & \times I_q((x_1 \dots x_m)^{-\gamma} Z | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i) d_q x_1 \dots d_q x_m \left. \right\} dZ \\ & = \int_{[0,1]^m} \prod_{j=1}^m x_j^{\sigma - \frac{j+1}{2}} (1-qx_j)^{\delta - \sigma - 1} \\ & \times \left\{ \int_{Z^N > 0} (\det Z)^{\rho - \frac{m+1}{2}} I_q((x_1 \dots x_m)^{-\gamma} Z | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i) dZ \right\} d_q x_1 \dots d_q x_m \\ & = \int_{[0,1]^m} \prod_{j=1}^m x_j^{\sigma + \frac{1-m}{2} \sum_{k=1}^N \gamma_k + \sum_{k=1}^N \gamma_k \rho_k - \frac{j+1}{2}} (1-qx_j)^{\delta - \sigma - 1} \end{aligned}$$

$$\begin{aligned}
 & \times \left\{ \int_{Z^N > 0} (\det(x_1 \dots x_m)^{-\gamma} Z)^{\rho - \frac{m+1}{2}} \right. \\
 & \times I_q((x_1 \dots x_m)^{-\gamma} Z | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i) d((x_1 \dots x_m)^{-\gamma} Z) \left. \right\} d_q x_1 \dots d_q x_m \\
 & = \left(\sum_{i=1}^r Q_{\bar{n}_i, \bar{a}_i, \alpha_i}^{p_i}(\rho) \right)^{-1} \times \\
 & \times \prod_{j=1}^m \int_0^1 x_j^{\sigma + \frac{1-m}{2}} \sum_{k=1}^N \gamma_k + \sum_{k=1}^N \gamma_k \rho_k - \frac{j-1}{2} - 1 (1 - qx_j)_{\delta - \sigma - 1} d_q x_j \\
 & = \left(\sum_{i=1}^r Q_{\bar{n}_i, \bar{a}_i, \alpha_i}^{p_i}(\rho) \right)^{-1} \\
 & \times \prod_{j=1}^m \Gamma_q(\delta - \sigma) \frac{\Gamma_q\left(\sigma + \frac{1-m}{2} \sum_{k=1}^N \gamma_k + \sum_{k=1}^N \gamma_k \rho_k - \frac{j-1}{2}\right)}{\Gamma_q\left(\delta + \frac{1-m}{2} \sum_{k=1}^N \gamma_k + \sum_{k=1}^N \gamma_k \rho_k - \frac{j-1}{2}\right)} \\
 & = \Gamma_q^m(\delta - \sigma) \left(\sum_{i=1}^r Q_{\bar{n}_i, \bar{a}_i, \alpha_i}^{p_i}(\rho) \right) \frac{\Gamma_{q,m}\left(\sigma + \frac{1-m}{2} \sum_{k=1}^N \gamma_k + \sum_{k=1}^N \gamma_k \rho_k\right)}{\Gamma_{q,m}\left(\delta + \frac{1-m}{2} \sum_{k=1}^N \gamma_k + \sum_{k=1}^N \gamma_k \rho_k\right)}.
 \end{aligned}$$

Thus, the second part of Theorem 3 is proved. In the same way, we can verify the first part too.

From (1) and properties of basic analogue gamma-function, we have

Theorem 4. We employ the notation $I_q(a_i - \text{sign}(n_{ij}))$, $i = 1, \dots, r$, $j = 1, \dots, p_i$ to denote contiguous function in (1), where $\Gamma_{q,m}^{n_{ij}}\left(a_{ij} + \sum_{k=1}^N \alpha_{ijk} \rho_k\right)$ is replaced by:

$$\begin{aligned}
 & \frac{(1 - q)^{m-1} \Gamma_{q,m}^{\text{sign}(n_{ij})}\left(a_{ij} - \text{sign}(n_{ij}) + \sum_{k=1}^N \alpha_{ijk} \rho_k\right)}{\prod_{t=1}^{m-1} \left(1 - q^{\left(a_{ij} + \sum_{k=1}^N \alpha_{ijk} \rho_k - \frac{t}{2} - \frac{1 + \text{sign}(n_{ij})}{2}\right)}\right)} \\
 & \times \Gamma_{q,m}^{n_{ij} - \text{sign}(n_{ij})}\left(a_{ij} + \sum_{k=1}^N \alpha_{ijk} \rho_k\right)
 \end{aligned}$$

but with all other parameters left unchanged. Then the following equalities are true:

a)

$$\begin{aligned}
 & I_q(a_{ik_0} + 1) - I_q(a_{ij_0} + 1) = \\
 & = \frac{q^{a_{ij_0}} - q^{a_{ik_0}}}{1 - q} q^{\left(\frac{1-m}{2} \sum_{t=1}^N \alpha_{ik_0 t}\right)} I_q(q^{-\alpha_{ik_0}} Z | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i),
 \end{aligned}$$

where $n_{ij_0} < 0, n_{ik_0} < 0, \alpha_{ik_0t} = \alpha_{ij_0t}, t = 1, \dots, N$.

b)

$$\begin{aligned} I_q(a_{ik_0} - 1) - I_q(a_{ij_0} - 1) &= \\ &= \frac{q^{a_{ij_0} - 1} - q^{a_{ik_0} - 1}}{1 - q} q^{\left(\frac{1-m}{2} \sum_{t=1}^N \alpha_{ik_0t}\right)} I_q(q^{-\alpha_{ik_0}} Z | r, p, \bar{n}_i, \bar{a}_i, \alpha_i), \end{aligned}$$

where $n_{ij_0} > 0, n_{ik_0} > 0, \alpha_{ik_0t} = \alpha_{ij_0t}, t = 1, \dots, N$.

c)

$$\begin{aligned} I_q(a_{ik_0} + 1) - I_q(a_{ij_0} - 1) &= \\ &= \frac{q^{a_{ij_0} - 1} - q^{a_{ik_0}}}{1 - q} q^{\left(\frac{1-m}{2} \sum_{t=1}^N \alpha_{ik_0t}\right)} I_q(q^{-\alpha_{ik_0}} Z | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i), \end{aligned}$$

where $n_{ij_0} > 0, n_{ik_0} < 0, \alpha_{ik_0t} = \alpha_{ij_0t}, t = 1, \dots, N$.

d)

$$\begin{aligned} I_q(a_{ik_0} - 1) - I_q(a_{ij_0} + 1) &= \\ &= \frac{q^{a_{ij_0}} - q^{a_{ik_0} - 1}}{1 - q} q^{\left(\frac{1-m}{2} \sum_{t=1}^N \alpha_{ik_0t}\right)} I_q(q^{-\alpha_{ik_0}} Z | r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i), \end{aligned}$$

where $n_{ij_0} < 0, n_{ik_0} > 0, \alpha_{ik_0t} = \alpha_{ij_0t}, t = 1, \dots, N$.

3. A Convolution for the M -Transform

Definition 2. [8] The M -transform of $f(Z)$ with N matrix arguments Z_1, Z_2, \dots, Z_N is defined by:

$$(Mf)(\rho) = \int_{Z^N > 0} (\det Z)^{\rho - \frac{m+1}{2}} f(Z) dZ, \tag{2}$$

where $(\det Z)^{\rho - \frac{m+1}{2}} = \prod_{j=1}^N (\det Z_j)^{\rho_j - \frac{m+1}{2}}$, ρ_j are complex numbers,

$\text{Re } \rho_j > \frac{m-1}{2}$, $Z = (Z_1, Z_2, \dots, Z_N)$, $dZ = dZ_1 dZ_2 \dots dZ_N$, $dZ_i = \prod_{j \geq k} dx_{ijk}$,

$Z_N > 0 = \{Z_j > 0, j = 1, \dots, N\}$, $Z_j > 0$ means that Z_j an $m \times m$ real symmetric positive definite matrix.

Definition 3. A convolution of two functions $f(Z), g(Z)$ with N matrix arguments Z_1, \dots, Z_n for M -transform (2) is defined as follows:

$${}_{Z^N}(f * g)(A) = \int_{Z^N > 0} (\det Z)^{-m} f(AZ^{-1})g(Z) dZ. \tag{3}$$

Theorem 5. Let $f, g \in L((\det Z)^{\rho - \frac{m+1}{2}}, Z^N > 0)$, then the convolution (3) belongs to $L((\det Z)^{\rho - \frac{m+1}{2}}, Z^N > 0)$, and

$$M[{}_{Z^N}(f * g)](\rho) = (Mf)(\rho)(Mg)(\rho),$$

where

$$\begin{aligned} L((\det Z)^{\rho - \frac{m+1}{2}}, Z^N > 0) &= \\ &= \left\{ f : \int_{Z^N > 0} |\det Z|^{\rho - \frac{m+1}{2}} |\det f(Z)| |dZ| < +\infty \right\}. \end{aligned}$$

Proof. We have

$$\begin{aligned} &\int_{A^N > 0} (\det A)^{\rho - \frac{m+1}{2}} {}_{Z^N}(f * g)(A) dA = \\ &= \int_{A^N > 0} (\det A)^{\rho - \frac{m+1}{2}} \left\{ \int_{Z^N > 0} (\det Z)^{-m} f(AZ^{-1})g(Z) dZ \right\} dA \\ &= \int_{Z^N > 0} (\det Z)^{-m} \left\{ \int_{A^N > 0} (\det A)^{\rho - \frac{m+1}{2}} f(AZ^{-1}) dA \right\} g(Z) dZ \\ &= \int_{Z^N > 0} (\det Z)^{-m} \left\{ \int_{U^N > 0} (\det UZ)^{\rho - \frac{m+1}{2}} (\det Z)^m f(U) dU \right\} g(Z) dZ \\ &= (Mf)(\rho)(Mg(\rho)), \end{aligned}$$

Further

$$\begin{aligned} &\int_{A^N > 0} |\det A|^{\rho - \frac{m+1}{2}} |\det {}_{Z^N}(f * g)(A)| |dA| \\ &\leq \int_{U^N > 0} |\det U|^{\rho - \frac{m+1}{2}} |\det f(U)| |dU| \int_{Z^N > 0} |\det Z|^{\rho - \frac{m+1}{2}} |\det g(Z)| |dZ| < +\infty. \end{aligned}$$

Therefore

$${}_{Z^N}(f * g) \in L((\det Z)^{\rho - \frac{m+1}{2}}, Z^N > 0).$$

Thus, Theorem 5 is proved. ■

Theorem 6. Let $A_1, A_2, \dots, A_N, Z_1, Z_2, \dots, Z_N$ be $m \times m$ symmetric matrices, functions g and h belong to $L((\det Z)^{\rho - \frac{m+1}{2}}, Z^N > 0)$, λ a complex constant such that $1 + \lambda Mg \neq 0$. Then there exists a function $k \in L((\det Z)^{\rho - \frac{m+1}{2}}, Z^N > 0)$, such that $Mk = \frac{\lambda Mg}{1 + \lambda Mg}$. Moreover, the integral equation

$$f(A) + \lambda \int_{Z^N > 0} (\det Z)^{-m} g(AZ^{-1})f(Z) dZ = h(A) \tag{4}$$

has a solution

$$f(A) = h(A) - {}_{Z^N}(k * h)(A) \in L((\det A)^{\rho - \frac{m+1}{2}}, A^N > 0).$$

Proof. From (4) and Theorem 5 we have

$$(Mf)(\rho) + \lambda(Mf)(\rho)(Mg)(\rho) = (Mh)(\rho).$$

Therefore

$$(Mf)(\rho) = \frac{1}{1 + \lambda(Mg)(\rho)}(Mh)(\rho).$$

On one hand, from Wiener-Levi Theorem it follows that there exists a function k , which belongs to $L((\det A)^{\rho - \frac{m+1}{2}}, A^N > 0)$ and satisfies:

$$(Mk)(\rho) = \frac{\lambda(Mg)(\rho)}{1 + \lambda(Mg)(\rho)}. \tag{6}$$

From (5) and (6) we have

$$(Mf)(\rho) = (Mh)(\rho) - (Mh)(\rho)(Mk)(\rho).$$

Consequently

$$f(A) = h(A) -_{Z^N} (k * h)(A)$$

From Theorem 5, it follows that $f(A) \in L((\det A)^{\rho - \frac{m+1}{2}}, A^N > 0)$.

Thus, Theorem 6 is proved. ■

Example. Let $A_i, Z_i, i = 1, \dots, N$ be $m \times m$ symmetric matrices, function $h(Z)$ belong to $L((\det Z)^{\rho - \frac{m+1}{2}}, Z^N > 0)$, $\text{Re } \rho_i > \frac{m-1}{2}$, the function $I_q(Z|r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i)$

be dominated by the function $\exp\left(-\sum_{i=1}^N \text{tr } Z_i\right)$, and

$$1 + \sum_{i=1}^r Q_{\bar{n}_i, \bar{a}_i, \alpha_i}^{\rho_i}(\rho) \neq 0.$$

Then the integral equation

$$f(A) + \int_{Z^N > 0} (\det Z)^{-m} I_q(AZ^{-1}|r, p_i, \bar{n}_i, \bar{a}_i, \alpha_i) f(Z) dZ = h(A)$$

has a solution

$$f(A) = h(A) -_{Z^N} (h * I_q(Z|r, p_i, \bar{n}_i, \bar{a}_i, \alpha; 1, 1, 0, a_1, \alpha_1))(A)$$

that belongs to $L((\det A)^{\rho - \frac{m+1}{2}}, A^N > 0)$.

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