

## Lagrange Multiplier Rule for Nonlinear Inequalities

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**Abstract.** The paper is about an alternative proof for the existence of nontrivial solutions (Lagrange multiplier rule) of nonlinear eigenvalue inequalities. An application to obstacle problems is given.

### 1. Introduction

We are concerned here with an eigenvalue inequality of the form

$$\langle Au - \lambda Bu, v - u \rangle \geq 0, \quad \forall v \in K, \quad (1)$$

( $K$  is a closed convex set in a Banach space) and some of its extensions. In the particular case where  $K \equiv X$ , (1) becomes the equation

$$A(u) - \lambda B(u) = 0. \quad (2)$$

An important result concerning the eigensolution is the Lagrange multiplier rule: “Let  $X$  be a Banach space and  $F, G : X \rightarrow \mathbb{R}$  be two Fréchet differential real functionals. If  $F$  achieves its minimum restricted to the set  $M = \{v \in X : G(v) = G(u)\}$  at the point  $u$  and if  $G'(u) \neq 0$ , then there exists  $\lambda \in \mathbb{R}$  such that  $F'(u) = \lambda G'(u)$ ”.

We now consider the more general unconstrained problem given by the inequality

$$\langle Au - \lambda Bu, v - u \rangle + \psi(v) - \psi(u) \geq 0, \quad \forall v \in X, \quad (3)$$

where  $\psi : X \rightarrow \mathbb{R} \cup \infty$  is an extended real proper and convex functional.

### 2. The Main Result

**Theorem 2.1.** *Let  $F, G$  be two Fréchet differential functionals on a normed linear space  $X$  with their Fréchet derivatives  $A, B : X \rightarrow X^*$ . Let  $\psi : X \rightarrow \mathbb{R} \cup \infty$*

be a proper, convex, extended real functional. Assume that:

- (i)  $F + \psi$  achieves its minimum on a non-empty set  $M = \{v \in X : G(v) = r\}$  for some real number  $r$  at  $u \in D(\psi)$ , where  $D(\psi)$  is the effective domain of  $\psi$ .
- (ii) There are  $h, k \in D(\psi)$  such that  $\langle Bu, h - u \rangle > 0$  and  $\langle Bu, k - u \rangle < 0$ . Then there exists at least one  $\lambda \in \mathbb{R}$  such that

$$\langle Au - \lambda Bu, v - u \rangle + \psi(v) - \psi(u) \geq 0, \quad \forall v \in X.$$

*Remark 1.*

- (i) This theorem generalizes the Lagrange multiplier rule. By letting  $\psi = 0$  we get  $A(u) = \lambda B(u)$ .
- (ii) Let  $K$  be a convex set in  $X$  and let  $\psi$  be the indicator function of  $K$ , it follows from (3) that

$$\langle Au - \lambda Bu, v - u \rangle \geq 0, \quad \forall v \in K.$$

- (iii) The theorem was first proved by Kubrusly in [4] using an indirect argument and was applied in [2] and [3] to solve the eigenvalue problems in Orlicz-Sobolev spaces.

*Proof.* It suffices to prove (4) for any  $v \in D(\psi)$ . From that observation we define

$$\begin{aligned} \Omega^+ &= \{v \in D(\psi) : \langle Bu, v - u \rangle > 0\} \\ \Omega^- &= \{v \in D(\psi) : \langle Bu, v - u \rangle < 0\} \\ \Omega^0 &= \{v \in D(\psi) : \langle Bu, v - u \rangle = 0\}. \end{aligned}$$

Then  $D(\psi) = \Omega^+ \cup \Omega^- \cup \Omega^0$ .

By the assumption  $\Omega^+ \neq \emptyset$  and  $\Omega^- \neq \emptyset$ . Now let  $v \in \Omega^+$  and  $w \in \Omega^-$ .

Given  $\epsilon > 0$ , we define for  $t, \alpha, \beta \geq 0$

$$f(t, \alpha, \beta) = u + t(v - u) + tb(w - u) + \alpha(v - u) + \beta(w - u),$$

where  $b = -\frac{\langle Bu, v - u \rangle}{\langle Bu, w - u \rangle} > 0$ .

Then

$$\begin{aligned} G(f(t, \alpha, \beta)) &= G(u) + t\langle Bu, v - u \rangle + tb\langle Bu, w - u \rangle + \alpha\langle Bu, v - u \rangle \\ &\quad + \beta\langle Bu, w - u \rangle + o(|t| + |\alpha| + |\beta|) \\ &= G(u) + \alpha\langle Bu, v - u \rangle + \beta\langle Bu, w - u \rangle + o(|t| + |\alpha| + |\beta|). \end{aligned}$$

Let  $\alpha, \beta \in [0, \epsilon t]$  then  $o(|t| + |\alpha| + |\beta|) = o(|t|)$ .

Furthermore, for  $t > 0$  sufficiently small,

$$\begin{cases} \text{if } \alpha = \epsilon t, \beta = 0 : G(f) > G(u), \\ \text{if } \alpha = 0, \beta = \epsilon t : G(f) < G(u). \end{cases}$$

Fix  $\beta = 0$ , let  $\alpha$  vary from  $\epsilon t$  to 0 then either  $G(f) - G(u)$  changes sign or  $G(f) > G(u)$  for all  $0 \leq \alpha \leq \epsilon t$ .

For the first case there is  $\alpha = \alpha(t) \in [0, \epsilon t]$  such that  $G(f) = G(u)$ . And for the second case, we fix  $\alpha = 0$  and let  $\beta$  vary from 0 to  $\epsilon t$ , there is  $\beta = \beta(t) \in [0, \epsilon t]$  such that  $G(f) = G(u)$ .

In general, for each  $t > 0$  there exist  $\alpha, \beta \in [0, \epsilon t]$  such that  $f(t, \alpha, \beta) \in M$  and thus for any  $t > 0$  sufficiently small

$$\begin{aligned}
0 &\leq F(f) + \psi(f) - F(u) - \psi(u) \\
&= F(f) - F(u) + \psi((1-t-tb-\alpha-\beta)u + (t+\alpha)v + (tb+\beta)w) - \psi(u) \\
&\leq \langle Au, t(v-u) + tb(w-u) + \alpha(v_u) + \beta(w-u) \rangle + o(|t|) \\
&\quad + (1-t-tb-\alpha-\beta)\psi(u) + (t+\alpha)\psi(v) + (tb+\beta)\psi(w) - \psi(u) \\
&= t[\langle Au, v-u \rangle + \psi(v) - \psi(u) + b(\langle Au, w-u \rangle + \psi(w) - \psi(u))] \\
&\quad + \alpha\langle Au, v-u \rangle + \beta\langle Au, w-u \rangle - (\alpha+\beta)\psi(u) + \alpha\psi(v) + \beta\psi(w) + o(|t|) \\
&\leq tc + 3(\alpha+\beta)M + o(|t|),
\end{aligned}$$

where

$$\begin{aligned}
c &= \langle Au, v-u \rangle + \psi(v) - \psi(u) + b(\langle Au, w-u \rangle + \psi(w) - \psi(u)) \\
&= \langle Bu, v-u \rangle \left[ \frac{\langle Au, v-u \rangle + \psi(v) - \psi(u)}{\langle Bu, v-u \rangle} - \frac{\langle Au, w-u \rangle + \psi(w) - \psi(u)}{\langle Bu, w-u \rangle} \right],
\end{aligned}$$

and  $M = \max\{|\psi(u)|, |\psi(v)|, |\psi(w)|, |\langle Au, v-u \rangle|, |\langle Au, w-u \rangle|\}$ .

Since  $\alpha, \beta \in [0, \epsilon t]$ ,

$$0 \leq tc + 6\epsilon Mt + o(|t|).$$

Dividing the above inequality by  $t$  and then let  $t \rightarrow 0^+$  we obtain

$$0 \leq c + 6\epsilon M.$$

Since  $\epsilon > 0$  is chosen arbitrarily, it follows that  $c \geq 0$ . Hence, for any  $v \in \Omega^+$  and  $w \in \Omega^-$  we have shown that:

$$\frac{\langle Au, v-u \rangle + \psi(v) - \psi(u)}{\langle Bu, v-u \rangle} - \frac{\langle Au, w-u \rangle + \psi(w) - \psi(u)}{\langle Bu, w-u \rangle} \geq 0.$$

Therefore,

$$\lambda_2 = \inf_{v \in \Omega^+} \frac{\langle Au, v-u \rangle + \psi(v) - \psi(u)}{\langle Bu, v-u \rangle} \geq \sup_{w \in \Omega^-} \frac{\langle Au, w-u \rangle + \psi(w) - \psi(u)}{\langle Bu, w-u \rangle} = \lambda_1.$$

Let  $\lambda$  be in  $[\lambda_1, \lambda_2]$ , it is easy to verify that

$$\langle Au - \lambda Bu, v-u \rangle + \psi(v) - \psi(u) \geq 0, \quad \forall v \in \Omega^+ \cup \Omega^-. \quad (5)$$

If  $v \in \Omega^0$ , define a sequence  $v_n = \frac{1}{n}h + \left(1 - \frac{1}{n}\right)v$ . Since  $D(\psi)$  is convex and

$\langle Bu, v_n - u \rangle = \frac{1}{n}\langle Bu, h - u \rangle > 0$ ,  $v_n \in \Omega^+$ . By (5),

$$\begin{aligned}
0 &\leq \langle Au - \lambda Bu, v_n - u \rangle + \psi(v_n) - \psi(u) \\
&\leq \langle Au - \lambda Bu, v_n - u \rangle + \frac{1}{n}\psi(h) + \left(1 - \frac{1}{n}\right)\psi(v) - \psi(u).
\end{aligned}$$

Let  $n \rightarrow \infty$  we obtain

$$\langle Au - \lambda Bu, v - u \rangle + \psi(v) - \psi(u) \geq 0, \quad \forall v \in \Omega^0. \quad (6)$$

Combining (5), (6) we have the theorem for any  $\lambda \in [\lambda_1, \lambda_2]$ .  $\blacksquare$

### 3. An Application to Obstacle Problems

Let  $\Omega$  be an open bounded domain in  $\mathbb{R}^N$ ,  $p > 1$  and  $q$  be such that the Sobolev the compact imbedding  $W^{1,p}(\Omega) \hookrightarrow L^q(\Omega)$  holds. Let  $f \in W_0^{1,p}(\Omega)$ ,  $f \geq 0$ . We will find  $(u, \lambda) \in K \times \mathbb{R}$  such that

$$\int_{\Omega} |\nabla u|^{p-2} \nabla u (\nabla v - \nabla u) - \lambda \int_{\Omega} |u|^{q-2} u (v - u) \geq 0, \quad \forall v \in K, \quad (7)$$

where  $K = \{u \in W_0^{1,p}(\Omega) : u \geq f \text{ on } \Omega\}$  is a closed convex set of  $W^{1,p}(\Omega)$ .

Let  $\psi$  be the indicator functional of  $K$ ; that is

$$\begin{cases} \psi(u) = 0, & \text{if } u \in K, \\ \psi(u) = \infty, & \text{otherwise.} \end{cases}$$

Now, let us define on  $W_0^{1,p}(\Omega)$ :

$$\begin{aligned} F(u) &= \frac{1}{p} \int_{\Omega} |\nabla u|^p dx, \\ G(u) &= \frac{1}{q} \int_{\Omega} u^q dx. \end{aligned}$$

Then the differential operators  $A, B$  of  $F, G$  (respectively) are given by

$$\begin{aligned} \langle Au, v \rangle &= \int_{\Omega} |\nabla u|^{p-2} \nabla u \nabla v dx, \\ \langle Bu, v \rangle &= \int_{\Omega} |u|^{q-2} u v dx. \end{aligned}$$

Let  $r > 0$  be a real number such that  $r > G(f)$ . By the compact imbedding  $W^{1,p}(\Omega) \hookrightarrow L^p(\Omega)$ ,  $G$  is weakly continuous and thus the level set  $G_r = \{u \in W_0^{1,p}(\Omega) : G(u) = r\}$  is weakly closed.

We observe that  $F$  is a norm in  $W_0^{1,p}(\Omega)$  and  $\psi$  is convex lower semi-continuous and positive. Thus  $F + \psi$  is weak lower semi-continuous and coercive on  $W_0^{1,p}(\Omega)$ . Hence  $F + \psi$  achieves its minimum on  $G_r$  at some  $u_r \in G_r$ .

Since  $(F + \psi)(u) = (F + \psi)(|u|)$ , we can assume  $u_r \geq 0$ . Moreover, by the choice of  $r$ ,  $u_r \neq f$ .

To apply the main theorem it remains to verify (ii). To see this, let  $v_1 = f$  and  $v_2 = 2u_r$  be in  $K$ , then

$$\begin{cases} \int_{\Omega} |u_r|^{q-2} u_r (v_1 - u_r) < 0, \\ \int_{\Omega} |u_r|^{q-2} u_r (v_2 - u_r) > 0. \end{cases}$$

Therefore, there is  $\lambda \in \mathbb{R}$  such that  $(u_r, \lambda)$  solves (7).

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