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# On Efficient Sets in $\mathbb{R}^2$

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**Abstract.** Let  $A \subset \mathbb{R}^2$  be a nonempty closed convex subset and  $C \subset \mathbb{R}^2$  be a nonempty nontrivial convex cone. Due to Luc (1985 and 1989), if A is compact and if the closure  $\overline{C}$  is pointed, then the efficient set E(A|C) of A w.r.t. C is homeomorphic to a nonempty closed interval of  $\mathbb{R}^1$ , whose proof was completed by Huy, Phuong, and Yen (2002). Huy (2003) extended this result by replacing the compactness of A with the compactness of  $A \cap (\{a\} - \overline{C})$ , for all  $a \in A$ . In this paper, we show the same conclusion in a much shorter way and under essentially weaker assumption, namely C is pointed and there exists an  $a \in A$  such that  $A \cap (\{a\} - C)$  is bounded. Moreover, the weakly efficient set  $E^w(A|C)$  w.r.t. any convex cone C having nonempty interior is homeomorphic to a closed interval in  $\mathbb{R}^1$  even if C is not pointed.

#### 1. Some Theorems on Efficient Sets

Let A be a nonempty subset of a real topological vector space X, which is partially ordered by a convex cone  $C \subset X$ .  $a \in A$  is said to be an *efficient point* of A w.r.t. C provided

there exists no 
$$b \in A \setminus \{a\}$$
 such that  $a - b \in C$ . (1)

This definition was often applied (e.g., in [1] and [2]) and it is used now throughout this paper. Another definition of efficient point a claims that

if 
$$a - b \in C$$
 for some  $b \in A$  then  $b - a \in C$ , (2)

as done, e.g., in [4, p. 39]. In fact, (1) and (2) are equivalent if C is a pointed cone defined by  $C \cap (-C) = \{0\}$  (see [4, p. 40]). But they are quite different if the ordering cone C is not pointed. So one must be careful when applying results in [4] for efficient points in the sense of (1) (as done in [2, p. 291]). For instance, Corollary 3.11 [4, p. 50] says that if X is finite-dimensional then each

compact nonempty set A possesses efficient points w.r.t. a convex cone C in the sense of (2), which is no more true in the sense of (1). For example, let

$$A = \{(0, y) \in \mathbb{R}^2 : 0 \le y \le 1\}, \quad C = \{(x, y) \in \mathbb{R}^2 : x \ge 0\},\$$

then each point of A is efficient w.r.t. C in the sense of (2), while A has no efficient point w.r.t. C in the sense of (1).

The set of efficient points of A w.r.t. C is called *efficient set* and denoted by E(A|C).

If the interior of C is nonempty and  $C' = \operatorname{int} C \cup \{0\}$ , then each  $a \in E(A|C')$  is named a weakly efficient point of A w.r.t. C, and the set of such points is called weakly efficient set and denoted by  $E^w(A|C)$ , i.e.,  $E^w(A|C) = E(A|C')$  (see [1, 2, 4]).

The purpose of [2] is to complete the proof of the following result, which was stated formerly in [3] and [4, p. 144].

**Theorem 1.** [2, p. 291] Let  $A \subset \mathbb{R}^2$  be a nonempty compact convex subset and  $C \subset \mathbb{R}^2$  be a nonempty convex cone whose closure  $\overline{C}$  is a pointed cone. Then the set E(A|C) is homeomorphic to a 0-dimensional or an 1-dimensional simplex.

Actually, the assertion of Theorem 1 fails if C is a trivial cone, because  $C = \{0\} \subset \mathbb{R}^2$  is a pointed convex cone but E(A|C) = A, i.e., dim  $E(A|C) = \dim A = 2$  is possible.

Using the preceding one, the next extended result was proven in [1], where  $A \subset \mathbb{R}^2$  is not necessarily compact but has compact sections w.r.t.  $\overline{C}$ , i.e.,

$$A \cap (\{a\} - \overline{C})$$
 is compact for all  $a \in A$ . (3)

**Theorem 2.** [1, p. 47] Suppose that  $C \subset \mathbb{R}^2$  is a convex cone whose interior is nonempty and whose closure is pointed, and  $A \subset \mathbb{R}^2$  is nonempty convex set having compact sections w.r.t.  $\overline{C}$ . Then the set E(A|C) (resp.,  $E^w(A|C)$ ) is homeomorphic to a 0-dimensional or an 1-dimensional polyhedral convex set. This amounts to saying that E(A|C) (resp.,  $E^w(A|C)$ ) is homeomorphic to one of the following four subsets of the real line:  $\{0\}$ , [0,1],  $[0,+\infty)$ ,  $(-\infty,+\infty)$ .

By the way, it is unnecessarily complicated to use 0-dimensional and 1-dimensional simplex or polyhedral convex set for describing intervals in  $\mathbb{R}$ . Therefore, we will not follow to use these notions.

The pointedness of  $\overline{C}$  as required in Theorems 1–2 is often assumed in the literature, sometimes by saying that C has a convex bounded base (see [4, p. 4]). This assumption is, from some points of view, a very strict restriction. Let us illustrate by considering the vector optimization problem

minimize 
$$F(x)$$
 subject to  $x \in A$ ,

where  $F:A\subset\mathbb{R}^n\to\mathbb{R}^m$ . If we use the concept of efficient points to investigate image set F(A), then  $\overline{C}=\mathbb{R}^m_+$ , which is pointed, but there is no need to study other forms of cone C. If F is a linear mapping and we use this concept to A, i.e., to investigate the optimal solution set, then  $\overline{C}$  is the intersection of

m halfspaces, which contains a line and is therefore not pointed, as long as m < n. For instance, consider for the special case n = 2 and m = 1 the linear optimization problem

minimize 
$$\xi_1 x_1 + \xi_2 x_2$$
 subject to  $(x_1, x_2) \in A \subset \mathbb{R}^2$ ,

where  $(\xi_1, \xi_2) \neq (0, 0)$ . Then, corresponding to (1) or (2), the ordering cone C must be chosen by

$$C = \{(c_1, c_2) \in \mathbb{R}^2 : \xi_1 c_1 + \xi_2 c_2 > 0\} \cup \{(0, 0)\}$$

$$\tag{4}$$

or

$$C = \{(c_1, c_2) \in \mathbb{R}^2 : \xi_1 c_1 + \xi_2 c_2 \ge 0\},\$$

respectively. In both cases, the closure  $\overline{C} = \{(c_1, c_2) \in \mathbb{R}^2 : \xi_1 c_1 + \xi_2 c_2 \geq 0\}$  is not pointed at all.

The main result of this paper is the following.

#### Theorem 3. Assume that

- $(A_1)$   $A \subset \mathbb{R}^2$  is a nonempty closed convex subset,
- $(A_2)$   $C \subset \mathbb{R}^2$  is a nonempty nontrivial pointed convex cone,
- $(A_3)$  there exists an  $a \in A$  such that  $A \cap (\{a\} C)$  is bounded.

Then the efficient set E(A|C) is homeomorphic to a nonempty closed interval in  $\mathbb{R}^1$ , which is bounded if A is bounded.

The replacement of the pointedness of  $\overline{C}$  (as required in Theorems 1–2) by the pointedness of C (as assumed in Theorem 3) is an essential extension. From the application point of view, it enables to cover some standard problems, which is impossible when requiring the pointedness of  $\overline{C}$ , as explained above. Obviously, the cone C given in (4) is pointed, but its closure not. We will come back to the technical point of view of this extension at the end of this paper.

If C is closed, then assumption  $(A_3)$  is equivalent to condition (3) required in Theorem 2, because

if a closed convex set 
$$S \subset \mathbb{R}^n$$
 contains  
some halfline with direction  $d$ , then it contains  
every halfline with direction  $d$  whose initial point is in  $S$ 

(see Proposition 2.5.1. [5, p. 75]). If C is not closed, then  $(A_3)$  is weaker than (3). To see it, just choose

$$A = \{(x, y) \in \mathbb{R}^2 : x \ge 0, \ y \le 0\},\$$

$$C = \{(x, y) \in \mathbb{R}^2 : x > 0, \ y \ge 0\} \cup \{(0, 0)\}.$$

Then  $A \cap (\{a\} - C) = \{a\}$  is bounded for all  $a \in \{(x, y) \in \mathbb{R}^2 : x = 0, y \leq 0\} \subset A$ , while  $A \cap (\{a\} - \overline{C})$  is unbounded for all  $a \in A$ . An important case for nonclosed C is given by (4).

Note that a nonempty closed interval in  $\mathbb{R}^1$  mentioned in Theorem 3 is homeomorphic to one of the four subsets mentioned at the end of Theorem 2.

If the nontrivial convex cone  $C \subset \mathbb{R}^2$  is not pointed, i.e., it is a closed halfspace, then the efficient set E(A|C) (in the sense of (1)) is either empty or a singleton.

Since  $E^w(A|C) = E(A|C')$  and  $C' = \text{int } C \cup \{0\}$  is pointed for every nontrivial convex C with int  $C \neq \emptyset$ , applying Theorem 3 to C' yields immediately the following.

Corollary 4. Suppose  $(A_1)$ ,  $(A_3)$ , and

 $(A_2')$   $C \subset \mathbb{R}^2$  is a nontrivial convex cone whose interior is nonempty. Then the weakly efficient set  $E^w(A|C)$  is homeomorphic to a nonempty closed interval in  $\mathbb{R}^1$ , which is bounded if A is bounded.

This result on the weakly efficient set  $E^w(A|C)$  is stronger than the one in Theorem 2, because (3) is now replaced by  $(A_3)$ , and C is no more claimed to be pointed.

#### 2. Proof of Theorem 3

Step 1: Existence of efficient points. By  $(A_3)$ , there exists an  $a \in A$  such that  $A \cap (\{a\} - C)$  is bounded, and following,  $B = \overline{A} \cap (\{a\} - C) \subset \mathbb{R}^2$  is nonempty and compact. Therefore, Corollary 3.11 [4, p. 50] implies that there exists at least an efficient point of B w.r.t. C in the sense of (2), which is equivalent to (1) for pointed C. It remains to show that  $E(B|C) \subset E(\underline{A|C})$ . Assume  $b \in E(B|C)$ . Then  $B \subset A \cap \overline{\{a\} - C}$  implies  $b \in A$  and  $b - a \in \overline{\{a\} - C} - \overline{\{a\} = -C}$ . For C is a pointed convex cone in  $\mathbb{R}^2$ , it is easy to deduce from the latter inclusion that  $b - a - c \in -C$ , or equivalently,

$$b - c \in \{a\} - C, \text{ for all } c \in C \setminus \{0\}.$$
 (6)

Hence, if  $b \notin E(A|C)$  then there exists  $c \in C \setminus \{0\}$  such that  $b-c \in A$ , which yields along with (6) that  $b-c \in A \cap (\{a\}-C) \subset B$ , a contradiction to  $b \in E(B|C)$ . Therefore,  $b \in E(A|C)$  must follow from  $b \in E(B|C)$ , i.e.,  $\emptyset \neq E(B|C) \subset E(A|C)$ .

Step 2: Homeomorphism F. By  $(A_3)$  and by rotation if necessary, we can assume that  $(0,1) \in C$ ,  $a \in A$ , and  $A \cap \{a - (0,\mu) : \mu \ge 0\}$  is bounded. Let

$$f(x) := \inf\{y \in \mathbb{R} : (x, y) \in A\},\$$

where  $\inf \emptyset = +\infty$ . Then (5) yields that  $f(x) > -\infty$  for all  $x \in \text{dom } f := \{x \in \mathbb{R} : f(x) < +\infty\}$ . Since A is closed,  $(x, f(x)) \in A$  for all  $x \in \text{dom } f$ . Moreover, both f and dom f are convex because A is convex.

Let  $x^- := \inf(\operatorname{dom} f)$  and  $x^+ := \sup(\operatorname{dom} f)$ . If  $x^- < x^+$ , then f is continuous in  $(x^-, x^+)$  (Theorem 5.5.1, [5, p. 224]). If, in addition,  $x^- > -\infty$ , then  $f(x^-) = \lim_{x \downarrow x^-} f(x)$  follows from the closedness and the convexity of A, i.e., f is

continuous on the right at  $x^-$ . Similarly, if  $x^- < x^+ < +\infty$ , then f is continuous on the left at  $x^+$ . Hence, f is continuous on the whole effective domain dom f.

Let  $Q := \{(x, f(x)) : x \in \text{dom } f\}$ . Then the mapping  $F : x \mapsto (x, f(x))$  from dom f onto Q is one-to-one, continuous, and its reverse mapping  $F^{-1}$ :

 $(x,f(x))\mapsto x$  is obviously continuous, too. That means F is a homeomorphism. Step 3: Convexity of  $F^{-1}(E(A|C))$ . Note that, by definition,  $E(A|C)\subset Q$ . Assume  $x_0,\ x_1\in F^{-1}(E(A|C)),\ x_0< x_1,\ \text{and}\ \lambda\in (0,1)$ . Let  $x_\lambda:=(1-\lambda)x_0+\lambda x_1$ . Consider an arbitrary  $(c_x,c_y)\in C\setminus\{(0,\mu):\mu\geq 0\}$  satisfying  $|c_x|\leqslant \min\{x_\lambda-x_0,\ x_1-x_\lambda\}$ . Since C is pointed and  $(0,1)\in C,\ c_x$  must be nonzero. If  $c_x<0$ , then the convexity of f implies

$$\frac{f(x_0 - c_x) - f(x_0)}{-c_x} \leqslant \frac{f(x_\lambda - c_x) - f(x_\lambda)}{-c_x}.$$

On the other hand,  $(x_0, f(x_0)) \in E(A|C)$ ,  $(0, -1) \in -C$ , and the convexity of -C yield  $f(x_0) - c_y < f(x_0 - c_x)$ , and therefore,

$$\frac{-c_y}{-c_x} = \frac{(f(x_0) - c_y) - f(x_0)}{-c_x} < \frac{f(x_0 - c_x) - f(x_0)}{-c_x}.$$

It follows from the preceding inequalities that

$$\frac{(f(x_{\lambda})-c_y)-f(x_{\lambda})}{-c_x} = \frac{-c_y}{-c_x} < \frac{f(x_{\lambda}-c_x)-f(x_{\lambda})}{-c_x}.$$

Hence,  $f(x_{\lambda}) - c_{\nu} < f(x_{\lambda} - c_{\nu})$ , and consequently,

$$(x_{\lambda}, f(x_{\lambda})) - (c_x, c_y) = (x_{\lambda} - c_x, f(x_{\lambda}) - c_y) \not\in A.$$

By using  $(x_1, f(x_1)) \in E(A|C)$ , we can prove similarly that the latter property is also true for  $c_x > 0$ . Since  $(x_\lambda, f(x_\lambda)) - (0, \mu) = (x_\lambda, f(x_\lambda) - \mu) \notin A$  for  $\mu > 0$ , A is convex and C is a cone, we obtain

$$(\{(x_{\lambda}, f(x_{\lambda}))\} + C) \cap A = \{(x_{\lambda}, f(x_{\lambda}))\},\$$

which implies

$$(x_{\lambda}, f(x_{\lambda})) \in E(A|C)$$
, i.e.,  $x_{\lambda} \in F^{-1}(E(A|C))$ .

Hence,  $F^{-1}(E(A|C))$  is convex, i.e., it is an interval in  $\mathbb{R}$ .

Step 4: Closedness of  $F^{-1}(E(A|C))$ . Denote

$$z^- := \inf F^{-1}(E(A|C))$$
 and  $z^+ := \sup F^{-1}(E(A|C))$ .

Since E(A|C) is nonempty,  $E(A|C) = \{z^-\}$  holds if  $z^- = z^+$ . Therefore, only case  $z^- < z^+$  must be checked.

Assume the contrary that  $z^- > -\infty$  but  $z^- \notin F^{-1}(E(A|C))$ , i.e.,

$$(z^-, f(z^-)) \not\in E(A|C).$$

Then there exists  $(c_x, c_y) \in C \setminus \{(0,0)\}$  such that  $(z^-, f(z^-)) - (c_x, c_y) \in A$ . By definition,  $c_x = 0$  is impossible.  $c_x > 0$  can be excluded by the same way as in Step 3 using the fact that  $(z, f(z)) \in E(A|C)$  for  $z \in (z^-, z^+)$ . If  $c_x < 0$ , then  $f(z^- - c_x) \leq f(z^-) - c_y$  follows from  $(z^- - c_x, f(z^-) - c_y) \in A$ . Since f is convex,  $f(z^- - tc_x) \leq f(z^-) - tc_y$  for all  $t \in [0, 1]$ . If there exists some  $t' \in (0, 1)$  with  $f(z^- - t'c_x) < f(z^-) - t'c_y$ , then, by the continuity of f,

$$f((z^- - t''c_x) - (t' - t'')c_x) = f(z^- - t'c_x) < f(z^- - t''c_x) - (t' - t'')c_y$$

holds for sufficiently small  $t'' \in (0, t')$ , which yields

$$(z^{-} - t''c_x, f(z^{-} - t''c_x)) - (t' - t'')(c_x, c_y) \in A,$$

a contradiction to  $(z, f(z)) \in E(A|C)$  for  $z \in (z^-, z^+)$ . Hence,  $f(z^- - tc_x) = f(z^-) - tc_y$  must be true for all  $t \in [0, 1]$ . But this implies

$$f((z^{-} - t''c_x) - (1 - t'')c_x) = f(z^{-} - c_x) = f(z^{-} - t''c_x) - (1 - t'')c_y,$$

i.e.,

$$(z^{-} - t''c_x, f(z^{-} - t''c_x)) - (1 - t'')(c_x, c_y) \in A,$$

for all  $t'' \in (0,1)$ , also a contradiction to  $(z, f(z)) \in E(A|C)$  for  $z \in (z^-, z^+)$ . Consequently, if  $z^- > -\infty$  then  $z^- \in F^{-1}(E(A|C))$ .

Similarly, it can be proven by the same way that  $z^+ \in F^{-1}(E(A|C))$  if  $z^+ < +\infty$ .

We have shown that  $F^{-1}(E(A|C))$  is a closed convex subset of  $\mathbb{R}$ , i.e., it is a closed interval. Obviously, if A is compact, so are E(A|C) and  $F^{-1}(E(A|C))$ , i.e.,  $F^{-1}(E(A|C))$  is a bounded closed interval. The proof of Theorem 3 is complete.

#### 3. Concluding Remarks

In the proof of [1]–[4], only the special case  $\overline{C} = \mathbb{R}^2_+$  was investigated, and other cases should be led to this one by nondegenerate linear transformation. Such a technique works only if  $\overline{C}$  is pointed, and it fails for pointed cones whose closure is not pointed (e.g., the cone given in (4)). Hence, from the technical point of view, the replacement of the pointedness of  $\overline{C}$  by the pointedness of C in Theorem 3 is a substantial extension, too.

Although the assumption of Theorem 3 is essentially weaker than the one of Theorems 1-2, we receive the same conclusion, and our proof is much shorter than the one of Theorems 1-2 given in [1]-[2].

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