

Short Communication

# On Linear Regular Multipoint Boundary-Value Problems for Differential Algebraic Equations

Pham Ky Anh and Nguyen Van Nghi

Department of Mathematics, Vietnam National University  
 334 Nguyen Trai Street, Hanoi, Vietnam

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## 1. Introduction

This paper deals with the so-called linear regular *multipoint boundary-value problems* (MPBVPs) for *differential-algebraic equations* (DAEs). It may be considered as a complement to works [1, 2], indicating further advantages of regular MPBVPs.

We begin by recalling some notations and concepts which will be frequently used in this article.

Let us consider the following linear MPBVP:

$$Lx := A(t)x' + B(t)x = q(t); \quad t \in J := [t_0, T], \quad (1)$$

$$\Gamma x := \int_{t_0}^T d\eta(t)x(t) = \gamma, \quad (2)$$

where  $A, B \in C(J, \mathbb{R}^{n \times n})$  are continuous matrix-valued functions with  $\det A(t) \equiv 0, \forall t \in J$ ;  $\eta \in BV(J, \mathbb{R}^{n \times n})$  is a matrix-valued function of bounded variations, and  $\gamma \in \mathbb{R}^n$  and  $q \in C := C(J, \mathbb{R}^n)$  are given vector and vector-valued function, respectively.

In the remainder of the paper we assume that the pair of matrices  $\{A, B\}$  satisfies the transferability condition [4], i.e.,

- (i) There exists a continuously differentiable projector-function  $Q \in C^1(J, \mathbb{R}^{n \times n})$ , i.e.,  $Q^2(t) = Q(t)$  such that  $\text{Im } Q(t) = \text{Ker } A(t)$  for all  $t \in J$ .
- (ii) The matrix  $G(t) := A(t) + B(t)Q(t)$  is non-singular for all  $t \in J$ .

Let  $P(t) := I - Q(t)$ , where  $I$  is the identity matrix, then  $P \in C^1(J, \mathbb{R}^{n \times n})$  and  $PQ = QP = 0$ ;  $P^2 = P$ .

Since

$$A(t)x' = A(t)[P(t)x(t)]' - A(t)P'(t)x(t), \tag{3}$$

we should restrict our consideration to the Banach space  $\mathcal{X} := \{x \in C : Px \in C^1(J, \mathbb{R}^n)\}$ , endowed with the norm  $\|x\| := \|x\|_\infty + \|(Px)'\|_\infty$ , where  $\|x\|_\infty = \max\{\|x(t)\| : t \in J\}$  and  $\|\cdot\|$  denotes a certain norm in  $\mathbb{R}^n$ .

From now on, we use the expression  $Ax'$  as an abbreviation of the right-hand side of (3).

Let  $Y(t)$  be the fundamental solution matrix of the following *initial-value problem* (IVP):  $Y' = (P'P_s - PG^{-1}B)Y$ ;  $Y(t_0) = I$ , where  $Q_s := QG^{-1}B$  and  $P_s := I - Q_s$  are canonical projections. It has been proved [4] that the matrix  $X(t) := P_s(t)Y(t)P(t_0)$ , with columns belonging to  $\mathcal{X}$ , satisfies the relations:

$$A(t)X' + B(t)X = 0; \quad P(t_0)(X(t_0) - I) = 0.$$

Moreover,  $\text{Ker } X(t) = \text{Ker } A(t)$  for every  $t \in J$ .

Now, define the so-called shooting matrix  $D := \int_{t_0}^T d\eta(t)X(t)$  and a closed subspace  $\text{Im } \Gamma := \{ \int_{t_0}^T d\eta(t)x(t) : x \in C \}$  of  $\mathbb{R}^n$ .

**Definition 1.** *The triplet  $\{A, B, \eta\}$  is said to be regular if the shooting matrix  $D$  satisfies the conditions:*

$$\text{Ker } D = \text{Ker } A(t_0); \quad \text{Im } D = \text{Im } \Gamma. \tag{4}$$

The regularity of  $\{A, B, \eta\}$  guarantees the well-posedness of MPBVP (1)–(2). More precisely, what can be proved is the following:

**Theorem 1.** [1] *The regularity of the triplet  $\{A, B, \eta\}$  is equivalent to the unique solvability of MPBVP (1)–(2) in the space  $\mathcal{X}$  for all  $q \in C$  and  $\gamma \in \text{Im } \Gamma$ . Moreover, the solution of (1)–(2) depends continuously on the data  $(q, \gamma)$ .*

From Theorem 1 and Banach's fixed point principle, one can derive an existence theorem for perturbed system:

$$Lx := A(t)x' + B(t)x = q(t) + \varepsilon f(x', x, t), \tag{5}$$

$$\Gamma x := \int_{t_0}^T d\eta(t)x(t) = \gamma + \varepsilon g(x). \tag{6}$$

**Theorem 2.** *Suppose that*

- (i) *The triplet  $\{A, B, \eta\}$  is regular.*
- (ii)  *$f : \mathbb{R}^n \times \mathbb{R}^n \times J \rightarrow \mathbb{R}^n$  is Lipschitz continuous in the first two variables, i.e.,*

$$\|f(\zeta, \varsigma, t) - f(\tilde{\zeta}, \tilde{\varsigma}, t)\| \leq c_1 \|\zeta - \tilde{\zeta}\| + c_2 \|\varsigma - \tilde{\varsigma}\| \quad \forall \zeta, \tilde{\zeta}, \varsigma, \tilde{\varsigma} \in \mathbb{R}^n; \quad \forall t \in J.$$

(iii)  $\text{Ker } A(t) \subset \text{Ker } f'_\zeta(\zeta, \varsigma, t) \quad \forall \zeta, \varsigma \in \mathbb{R}^n; \forall t \in J$ . Here,  $f$  is assumed to be continuously differentiable in the first variable and  $f'_\zeta$  denotes the corresponding partial derivative.

(iv) The nonlinear boundary operator  $g : C \rightarrow \text{Im } \Gamma$  is Lipschitz continuous, i.e.,  $\|g(x) - g(y)\| \leq c_3 \|x - y\|_\infty; \forall x, y \in C$ .

Then for a sufficiently small  $\varepsilon > 0$ , problem (5), (6) is uniquely solvable for all  $q \in C$  and  $\gamma \in \text{Im } \Gamma$ . Moreover, the iterative process:  $A(t)x'_{n+1} + B(t)x_{n+1} = q(t) + \varepsilon f(x'_n, x_n, t); \int_{t_0}^T d\eta(t)x_{n+1}(t) = \gamma + \varepsilon g(x_n)$  is convergent at a geometrical rate.

Using Theorems 1 and 2, we can prove the regularity of some perturbed systems.

**Proposition 1.** *The regularity of the triplet  $\{A, B, \eta\}$  is stable under small perturbation of  $B \in C(J, \mathbb{R}^{n \times n})$ , i.e., if  $\{A, B, \eta\}$  is regular, then, for any  $C \in C(J, \mathbb{R}^{n \times n})$  and for a sufficiently small  $\varepsilon > 0$ , the triplet  $\{A, B + \varepsilon C, \eta\}$  is also regular.*

**Proposition 2.** *Suppose that  $\{A, B, \eta\}$  is a regular triplet. Then, for a sufficiently small  $\varepsilon > 0$ , the triplet  $\{A + \varepsilon BP, B + \varepsilon BPP', \eta\}$  is also regular.*

We note that the pairs  $\{A, B + \varepsilon C\}$  and  $\{A + \varepsilon BP, B + \varepsilon BPP'\}$  in Propositions 1 and 2, respectively, are transferable.

**Proposition 3.** *Suppose that:*

(i)  $\{A, B, \eta\}$  is a regular triplet.

(ii) The perturbed boundary operator  $\Gamma_\varepsilon(x) := \int_{t_0}^T d\eta_\varepsilon(t)x(t)$  with  $\eta_\varepsilon \in BV(J, \mathbb{R}^{n \times n})$  satisfies two conditions:

(a)  $\text{Im } \Gamma_\varepsilon \subset \text{Im } \Gamma$ .

(b) The total variation  $V_{t_0}^T(\eta - \eta_\varepsilon)$  is not greater than  $\varepsilon$ .

Then, for a sufficiently small  $\varepsilon > 0$ , the triplet  $\{A, B, \eta_\varepsilon\}$  is also regular.

From now on, let us consider a special MPBVP (1), (2) with  $\eta(t) = \int_{t_0}^t C(s)ds$ , where  $C \in C(J, \mathbb{R}^{n \times n})$ . Introducing a new variable  $y(t) := \int_{t_0}^t C(s)x(s)ds$ , we can reduce (1), (2) to a two-point BVP for an enlarged system:

$$\bar{A}(t)z' + \bar{B}(t)z = \bar{q}(t), \tag{7}$$

$$Mz(t_0) + Nz(T) = \bar{\gamma}, \tag{8}$$

where  $\bar{A} := \begin{pmatrix} A & 0 \\ 0 & I \end{pmatrix}; \bar{B} := \begin{pmatrix} B & 0 \\ -C & 0 \end{pmatrix}; M := \begin{pmatrix} 0 & 0 \\ 0 & I \end{pmatrix}; N := \begin{pmatrix} 0 & I \\ 0 & 0 \end{pmatrix};$   
 $\bar{\gamma} := \begin{pmatrix} \gamma \\ 0 \end{pmatrix}; \bar{q} := \begin{pmatrix} q \\ 0 \end{pmatrix}; z := \begin{pmatrix} x \\ y \end{pmatrix}.$

Obviously, boundary condition (8) can be rewritten as:  $\bar{\Gamma}z := \int_{t_0}^T d\bar{\eta}z(t) = \bar{\gamma}$  with

$$\bar{\eta}(t) = \begin{cases} -M & t = t_0 \\ 0 & t_0 < t < T \\ N & t = T. \end{cases}$$

Defining the enlarged projections  $\bar{Q} = \begin{pmatrix} Q & 0 \\ 0 & 0 \end{pmatrix}$ ;  $\bar{P} = \bar{I} - \bar{Q} := \begin{pmatrix} P & 0 \\ 0 & I \end{pmatrix}$  and taking into account the fact that  $\bar{G} = \bar{A} + \bar{B}\bar{Q} := \begin{pmatrix} G & 0 \\ -CQ & I \end{pmatrix}$ ;  $\bar{G}^{-1} := \begin{pmatrix} G^{-1} & 0 \\ CQG^{-1} & I \end{pmatrix}$ , we come to the conclusion that the pair  $\{\bar{A}, \bar{B}\}$  is also transferable.

However, if  $\text{Im } \Gamma \neq \mathbb{R}^n$ , then the triplet  $\{\bar{A}, \bar{B}, \bar{\eta}\}$  is not regular with respect to the space  $\bar{X} = \{z = (x, y)^T \in C : Px, y \in C^1\}$ .

Thus, it should be more rational to implement approximate methods directly to regular MPBVPs than to enlarged two-point BVPs.

Let  $t_0 < t_1 < \dots < t_m = T$  be a given partition of the interval  $J = [t_0, T]$ . Denote by  $X_i(t)$  the fundamental matrix satisfying relations  $A(t)X_i' + B(t)X_i = 0$ ,  $t \in [t_i, t_{i+1}]$ ;  $P_i[X_i(t_i) - I] = 0$  ( $i = 0, \dots, m - 1$ ), where  $P_i := P(t_i)$ .

We are looking for a solution of (1), (2) of the form

$$x(t) = x(t, s_0, s_1, \dots, s_{m-1}) := x_i(t) \text{ if } t \in [t_i, t_{i+1}], \quad (i = 0, \dots, m - 1),$$

where  $x_i(t)$  is a solution of the IVP:

$$\begin{cases} A(t)x_i' + B(t)x_i = q(t), \\ P_i(x_i(t_i) - s_i) = 0. \end{cases} \quad (9)$$

The shooting vectors  $s_i$  ( $i = 0, \dots, m - 1$ ) are defined from the matching conditions:

$$P_i(x_{i-1}(t_i) - s_i) = 0 \quad (10)$$

and the boundary condition (2):

$$\int_{t_0}^T C(t)x(t)dt = \sum_{i=0}^{m-1} \int_{t_i}^{t_{i+1}} C(t)x_i(t)dt = \gamma. \quad (11)$$

According to [4],  $x(t, s_0, \dots, s_{m-1})$  is a solution of (1) and therefore, by virtue of (11), it is also a (unique) solution of (1), (2).

Denote by  $Y_i(t)$  the fundamental matrix of the IVP:  $Y_i' = (P'P_s - PG^{-1}B)Y_i$ ;  $Y_i(t_i) = I$ ;  $t \in [t_i, t_{i+1}]$  ( $i = 0, \dots, m - 1$ ).

From (9), it follows that

$$x_i(t) = X_i(t)s_i + f_i(t); \quad t \in [t_i, t_{i+1}] \quad (i = 0, \dots, m - 1), \quad (12)$$

where

$$f_i(t) = X_i(t) \int_{t_i}^t Y_i^{-1}(\tau) P_s(\tau) (I + P'(\tau)) G^{-1}(\tau) q(\tau) d\tau + Q(t) G^{-1}(t) q(t).$$

The matching condition (10) implies that

$$P_i(X_{i-1}(t_i) s_{i-1} - s_i) = r_i, \tag{13}$$

where  $r_i = -P_i f_{i-1}(t_i)$ . Using (11), we have

$$\sum_{i=0}^{m-1} C_i s_i = \bar{\gamma}, \tag{14}$$

where  $C_i = \int_{t_i}^{t_{i+1}} C(t) X_i(t) dt$  and  $\bar{\gamma} = \gamma - \sum_{i=0}^{m-1} \int_{t_i}^{t_{i+1}} C(t) f_i(t) dt$ . Let  $Q_i := I - P_i$ .

**Theorem 3.** *Let  $\{A, B, \eta\}$  be a regular triplet. Then the shooting vectors  $\{s_i\}_{i=0}^{m-1}$  satisfying conditions (13), (14) and additional relations  $Q_i s_i = 0$  ( $i = 0, \dots, m-1$ ) are uniquely determined. Moreover, the solution of MPBVP (1), (2) is given by (12).*

Finally, let us consider a MPBVP for a weakly non-linear DAE:

$$Lx := A(t)x' + B(t)x = q(t) + \varepsilon f(x, t), \tag{15}$$

$$\Gamma x := \int_{t_0}^T C(t)x(t)dt = \gamma. \tag{16}$$

Suppose that the triplet  $\{A, B, \eta\}$  is regular and the non-linear part  $f(x, t)$  is Lipschitz continuous in  $x$ . From Theorem 2, it follows that for a sufficiently small  $\varepsilon > 0$ , MPBVP (15), (16) has a unique solution and the Picard method applied to (15), (16) is convergent. However, avoiding the stiffness effect of the left-hand side of (15), we should implement the multiple iteration method (see [3]) for solving (15), (16).

Suppose that the  $(j-1)$ th iteration  $x^{j-1}(t)$  has been found. Then the next approximation  $x^j(t)$  can be defined as

$$x^j(t) = x_i^j(t), \quad t \in [t_i, t_{i+1}] \quad (i = 0, \dots, m-1),$$

where  $x^0(t)$  is a solution of linear MPBVP (1), (2) obtained by the above-mentioned multishooting method, and  $A(t)(x_i^j)' + B(t)x_i^j = q(t) + \varepsilon f(x^{j-1}, t)$ ;  $P_i(x_i^j(t_i) - s_i^j) = 0$  ( $j \geq 1$ ). The matching conditions give  $P_i(x_{i-1}^j(t_i) - s_i^j) = 0$ . Further, from boundary condition (16) we get  $\sum_{i=0}^{m-1} \int_{t_i}^{t_{i+1}} C(t)x_i^j(t)dt = \gamma$ . Thus, we define

$$x_i^j(t) = X_i(t)s_i^j + f_i^j(t), \quad t \in [t_i, t_{i+1}], \tag{17}$$

where

$$f_i^j(t) = X_i(t) \int_{t_i}^t Y_i^{-1}(\tau) P_s(\tau) (I + P'(\tau)) G^{-1}(\tau) [q(\tau) + \varepsilon f(x^{j-1}, \tau)] d\tau + Q(t) G^{-1}(t) [q(t) + \varepsilon f(x^{j-1}, t)].$$

Putting

$$r_i^j = -P_i f_{i-1}^j(t_i); \quad \gamma^j = \gamma - \sum_{i=0}^{m-1} \int_{t_i}^{t_{i+1}} C(t) f_i^j(t) dt,$$

we come to a system, similar to those of (13), (14):

$$\sum_{i=0}^{m-1} C_i s_i^j = \gamma^j; \quad P_i X_{i-1}(t_i) s_{i-1}^j - P_i s_i^j = r_i^j \quad (i = 1, \dots, m - 1).$$

Adding to this system  $m$  relations  $Q_i s_i^j = 0 \quad (i = 0, \dots, m - 1)$ , we can define the shooting vectors  $s_i^j$  and then determine  $x_i^j(t) \quad (i = 0, \dots, m - 1)$  by (17).

**Theorem 4.** *Suppose that the triplet  $\{A, B, \eta\}$  is regular and  $f(x, t)$  is Lipschitz continuous in  $x$ . Then, for a sufficiently small  $\varepsilon > 0$ , the multiple iteration method is convergent at a geometrical rate.*

Detailed proofs and numerical experiments will be given in a forthcoming paper.

**References**

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