# Iterative Method for Solving a Boundary Value Problem for Triharmonic Equation* 

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#### Abstract

Recently we have developed the boundary operator method and the parametric extrapolation technique for solving a boundary value problem (BVP) for second order elliptic equation with discontinuous coefficients and BVPs for biharmonic and biharmonic type equations. In this paper we use these methods for a BVP for triharmonic equation. Namely, two iterative schemes, which reduce the original problem to a sequence of BVPs for the Poisson equation, are proposed and investigated.


## 1. Introduction

In earlier papers we have developed the boundary operator method and the parametric extrapolation technique for solving iteratively a BVP for second order elliptic equation with discontinuous coefficients [1], BVPs for biharmonic and biharmonic type equations [2-4]. The idea of the method is to reduce a complicated BVP to a sequence of simpler problems, for which there are available many efficient methods of solving. In this paper we apply this method to the following BVP for triharmonic equation

$$
\begin{align*}
& \Delta^{3} u=f(x), \quad x \in \Omega  \tag{1}\\
&\left.u\right|_{\Gamma}=0,\left.\quad \frac{\partial u}{\partial \nu}\right|_{\Gamma}=0,\left.\quad \Delta u\right|_{\Gamma}=0 \tag{2}
\end{align*}
$$

[^0]where $\Delta$ is the Laplace operator, $\Omega$ is a bounded domain in $R^{n}(n \geq 2), \Gamma$ is the sufficiently smooth boundary of $\Omega$. The solvability and smoothness of the solution of problem (1)-(2) follow from the general theory of elliptic problems (see [6]), namely, if $f \in H^{s}(\Omega)$ then there exists a unique solution $u \in H^{s+6}(\Omega)$ . Here, as usual, $H^{s}(\Omega)$ is a Sobolev space.

## 2. Reduction of BVP to Boundary Operator Equation

We set

$$
\Delta u=v, \Delta v=w
$$

and denote by $w_{0}$ the trace of $w$ on $\Gamma$, i.e. $w_{0}=\left.w\right|_{\Gamma}$. Then from (1)-(2) we come to the sequence of problems

$$
\begin{array}{rlrl}
\Delta w & =f, & x \in \Omega, & \left.w\right|_{\Gamma}=w_{0} \\
\Delta v & =w, & x \in \Omega, & \left.v\right|_{\Gamma}=0  \tag{3}\\
\Delta u=v, & x \in \Omega, & \left.u\right|_{\Gamma}=0 .
\end{array}
$$

The solution $u$ from above problems should satisfy the second condition in (2). Now, we introduce the operator $B$ defined on boundary functions $w_{0}$ by the formula

$$
\begin{equation*}
B w_{0}=-\left.\frac{\partial u}{\partial \nu}\right|_{\Gamma} \tag{4}
\end{equation*}
$$

where $u$ is found from the sequence of problems

$$
\begin{align*}
\Delta w & =0, & x \in \Omega, & \left.w\right|_{\Gamma}=w_{0}, \\
\Delta v & =w, & x \in \Omega, & \left.v\right|_{\Gamma}=0  \tag{5}\\
\Delta u & =v, & x \in \Omega, & \left.u\right|_{\Gamma}=0 .
\end{align*}
$$

Notice that the operator $B$ primarily defined on smooth functions is extended by continuity on the whole $L_{2}(\Gamma)$. Its properties will be investigated later.

It is not difficult to verify
Theorem 1. Suppose that $u$ is the solution of the original problem (1)-(2). Then $w_{0}=\left.\Delta^{2} u\right|_{\Gamma}$ satisfies the operator equation

$$
\begin{equation*}
B w_{0}=F, \tag{6}
\end{equation*}
$$

where

$$
\begin{equation*}
F=\left.\frac{\partial u_{2}}{\partial \nu}\right|_{\Gamma} \tag{7}
\end{equation*}
$$

$u_{2}$ being determined from the problems

$$
\begin{align*}
\Delta w_{2} & =f, \quad x \in \Omega,\left.\quad w_{2}\right|_{\Gamma}=0 \\
\Delta v_{2}=w_{2}, & x \in \Omega,\left.\quad v_{2}\right|_{\Gamma}=0  \tag{8}\\
\Delta u_{2}=v_{2}, & x \in \Omega,\left.\quad u_{2}\right|_{\Gamma}=0 .
\end{align*}
$$

Notice that if $f \in H^{s}(\Omega)$ then $F \in H^{s+9 / 2}(\Gamma)$. Thus, we have led the original problem to the operator equation (6) for finding $w_{0}$. After $w_{0}$ is found, by solving the problems (3) we shall find the solution of (1)-(2).

Now, let us study the properties of $B$. First, for short we denote by $H$ the Hilbert space $L_{2}(\Gamma)$ with the scalar product (., .).

Property 1. $B$ is symmetric and positive in $H$.
Proof. For any functions $w_{0}$ and $\bar{w}_{0}$ we have

$$
\begin{aligned}
\left(B w_{0}, \bar{w}_{0}\right) & =\int_{\Gamma} \bar{w}_{0} B w_{0} d \Gamma=-\int_{\Gamma} \bar{w}_{0} \frac{\partial u}{\partial \nu} d \Gamma=\int_{\Gamma}\left(u \frac{\partial \bar{w}}{\partial \nu}-\bar{w}_{0} \frac{\partial u}{\partial \nu}\right) d \Gamma \\
& =\int_{\Omega}(u \Delta \bar{w}-\bar{w} \Delta u) d x=-\int_{\Omega} \bar{w} \Delta u d x \\
& =-\int_{\Omega} \Delta \bar{v} v d x=\int_{\Omega} \operatorname{grad} v \cdot \operatorname{grad} \bar{v} d x
\end{aligned}
$$

in view of (5) and the same equalities for $\bar{w}_{0}, \bar{u}, \bar{v}$ and $\bar{w}$. Thus, we obtain

$$
\left(B w_{0}, \bar{w}_{0}\right)=\int_{\Omega} \operatorname{grad} v \cdot \operatorname{grad} \bar{v} d x
$$

Hence,

$$
\left(B w_{0}, \bar{w}_{0}\right)=\left(B \bar{w}_{0}, w_{0}\right)
$$

The symmetry of $B$ is proved.
Furthermore, we have

$$
\left(B w_{0}, w_{0}\right)=\int_{\Omega}|\operatorname{grad} v|^{2} d x \geq 0
$$

The equality occurs if and only if $w_{0}=0$. So, $B$ is positive and Property 1 is proved.

Property 2. $B$ is a completely continuous operator in $H$.
Proof. From [6] it follows that $B$ is an isomorphism of spaces $H^{s}(\Gamma)$ and $H^{s+3}(\Gamma)$, $s \geq 0$. Due to the compactness of embedding of $H^{s+3}(\Gamma)$ into $H^{s}(\Gamma)$ we get that $B$ is completely continuous operator in $H^{s}(\Gamma)$. In particular, $B$ is a completely continuous in $H=H^{0}(\Gamma)=L_{2}(\Gamma)$.

## 3. Iterative Method for BVP (1)-(2)

Consider the following iterative method for (1)-(2):
i) Give a starting approximation $w_{0}^{(0)} \in H^{1 / 2}(\Gamma)$.
ii) Knowing $w_{0}^{(k)},(k=0,1, \ldots$,$) solve successively three problems$

$$
\begin{align*}
& \Delta w^{(k)}=f, \quad x \in \Omega,\left.\quad w^{(k)}\right|_{\Gamma}=w_{0}^{(k)} \\
& \Delta v^{(k)}=w^{(k)}, \quad x \in \Omega,\left.\quad v^{(k)}\right|_{\Gamma}=0  \tag{9}\\
& \Delta u^{(k)}=v^{(k)}, \quad x \in \Omega,\left.\quad u^{(k)}\right|_{\Gamma}=0
\end{align*}
$$

iii) Compute the new approximation of $w_{0}$

$$
\begin{equation*}
w_{0}^{(k+1)}=w_{0}^{(k)}-\tau \frac{\partial u^{(k)}}{\partial \nu}, \quad x \in \Gamma \tag{10}
\end{equation*}
$$

where $\tau$ is a sufficiently small iterative parameter.
Theorem 2. The above iterative process is a realization of the following iterative scheme

$$
\begin{equation*}
\frac{w_{0}^{(k+1)}-w_{0}^{(k)}}{\tau}+B w_{0}^{(k)}=F \tag{11}
\end{equation*}
$$

for the operator equation (6).
Proof. Indeed, if we represent $u^{(k)}=u_{1}^{(k)}+u_{2}, v^{(k)}=v_{1}^{(k)}+v_{2}, w^{(k)}=w_{1}^{(k)}+w_{2}$, where $u_{2}, v_{2}, w_{2}$ are the solutions of (8) then $u_{1}^{(k)}, v_{1}^{(k)}, w_{1}^{(k)}$ satisfy the following problems

$$
\begin{align*}
\Delta w_{1}^{(k)} & =0, \quad x \in \Omega,\left.\quad w_{1}^{(k)}\right|_{\Gamma}=w_{0}^{(k)} \\
\Delta v_{1}^{(k)} & =w_{1}^{(k)}, \quad x \in \Omega,\left.\quad v_{1}^{(k)}\right|_{\Gamma}=0  \tag{12}\\
\Delta u_{1}^{(k)} & =v_{1}^{(k)}, \quad x \in \Omega,\left.\quad u_{1}^{(k)}\right|_{\Gamma}=0
\end{align*}
$$

By the definition of $B$ we have

$$
\begin{equation*}
B w_{0}^{(k)}=-\left.\frac{\partial u_{1}^{(k)}}{\partial \nu}\right|_{\Gamma} \tag{13}
\end{equation*}
$$

Taking into account

$$
\frac{\partial u^{(k)}}{\partial \nu}=\frac{\partial u_{1}^{(k)}}{\partial \nu}+\frac{\partial u_{2}}{\partial \nu}
$$

from (10), (13) and (7) we obtain (11) and the theorem is proved.
Since $B$ is shown to be a symmetric, positive, completely continuous operator in $H$ there holds

Theorem 3. The iterative method (11) is convergent if

$$
0<\tau<\frac{2}{\|B\|}
$$

Proof. See Lemma 2.1 in [4].

## 4. Accelerated Iterative Method for BVP (1)-(2)

In order to construct a faster convergent iterative process for (1)-(2) we shall use the parametric extrapolation technique, which was developed and used in our works [1-4]. For this reason we consider the perturbed problem

$$
\begin{align*}
& \Delta^{3} u_{\delta}=f(x), \quad x \in \Omega \\
& \left.u_{\delta}\right|_{\Gamma}=0,\left.\quad \Delta u_{\delta}\right|_{\Gamma}=0 \\
& \left.\left(\frac{\partial u_{\delta}}{\partial \nu}-\delta \Delta^{2} u_{\delta}\right)\right|_{\Gamma}=0 \tag{14}
\end{align*}
$$

Analogously as in Sec. 2, it is easy to show that this problem may be reduced to the following operator equation

$$
\begin{equation*}
B_{\delta} w_{\delta 0}=F \tag{15}
\end{equation*}
$$

where $B_{\delta}=B+\delta I, w_{\delta 0}=\left.\Delta^{2} u_{\delta}\right|_{\Gamma}, I$ is the identity operator and $B$ and $F$ are defined by (4)-(5) and (7)-(8), respectively. Taking into account the property 1 of $B$ we see that $B_{\delta}$ is a linear, symmetric, positive definite operator in $H$ and $B_{\delta} \geq \delta I$.

Theorem 4. Suppose that $f \in H^{s-6}(\Omega), s \geq 6$. Then for the solution of the problem (14) there holds the following asymptotic expansion

$$
\begin{equation*}
u_{\delta}=u+\sum_{i=1}^{N} \delta^{i} y_{i}+\delta^{N+1} z_{\delta}, \quad x \in \Omega, \quad 0 \leq 3 N \leq s-5 / 2 \tag{16}
\end{equation*}
$$

where $y_{0}=u$ is the solution of $(1)-(2), y_{i} \quad(i=1, \ldots, N)$ are functions independent of $\delta, y_{i} \in H^{s-3 i}(\Omega), z_{\delta} \in H^{s-3 N}(\Omega)$ and

$$
\begin{equation*}
\left\|z_{\delta}\right\|_{H^{2}(\Omega)} \leq C_{1} \tag{17}
\end{equation*}
$$

$C_{1}$ being independent of $\delta$.
Proof. Under the assumption of the theorem, by [6] there exists a unique solution $u \in H^{s}(\Omega)$ of the problem (14). After substituting (16) into (14) and comparing coefficients of the same powers of $\delta$ we see that $y_{i}$ and $z_{\delta}$ satisfy the following problems

$$
\begin{gather*}
\Delta^{3} y_{i}=0, \quad x \in \Omega \\
\left.y_{i}\right|_{\Gamma}=0,\left.\quad \Delta y_{i}\right|_{\Gamma}=0  \tag{18}\\
\left.\frac{\partial y_{i}}{\partial \nu}\right|_{\Gamma}=\left.\Delta^{2} y_{i-1}\right|_{\Gamma}, i=1, \ldots, N \\
\Delta^{3} z_{\delta}=0, \quad x \in \Omega \\
\left.z_{\delta}\right|_{\Gamma}=0,\left.\quad \Delta z_{\delta}\right|_{\Gamma}=0 \\
\left.\left(\frac{\partial z_{\delta}}{\partial \nu}-\delta \Delta^{2} z_{\delta}\right)\right|_{\Gamma}=\left.\Delta^{2} y_{N}\right|_{\Gamma} \tag{19}
\end{gather*}
$$

Once again, using [6] it is not difficult to establish successively that (18) has a unique solution $y_{i} \in H^{s-3 i}(\Omega)$ and (19) has a unique solution $z_{\delta} \in H^{s-3 N}(\Omega)$. Clearly, $y_{i}(i=1, \ldots, N)$ do not depend on $\delta$. It remains to estimate $z_{\delta}$. For this purpose we reduce (19) to a boundary operator equation. We set

$$
\begin{equation*}
\Delta z_{\delta}=v_{\delta}, \Delta v_{\delta}=w_{\delta} \tag{20}
\end{equation*}
$$

and denote $\left.w_{\delta}\right|_{\Gamma}=w_{\delta 0}$. Then we get

$$
\begin{array}{rlrl}
\Delta w_{\delta} & =f, \quad x \in \Omega,\left.\quad w_{\delta}\right|_{\Gamma}=w_{\delta 0}, \\
\Delta v_{\delta} & =w_{\delta}, & x \in \Omega,\left.\quad v_{\delta}\right|_{\Gamma}=0  \tag{21}\\
\Delta z_{\delta} & =v_{\delta}, & x \in \Omega,\left.\quad z_{\delta}\right|_{\Gamma}=0
\end{array}
$$

By the definition of $B$ we have

$$
\begin{equation*}
B w_{\delta 0}=-\left.\frac{\partial z_{\delta}}{\partial \nu}\right|_{\Gamma} \tag{22}
\end{equation*}
$$

Now, using the last condition of (19) we obtain

$$
\begin{equation*}
B w_{\delta 0}+\delta I w_{\delta 0}=h \tag{23}
\end{equation*}
$$

where $h=-\left.\Delta^{2} y_{N}\right|_{\Gamma}$.
It is not hard to verify that (see [5])

$$
\begin{equation*}
\left(B w_{\delta 0}, w_{\delta 0}\right) \leq\left(B w_{0}, w_{0}\right) \tag{24}
\end{equation*}
$$

where $w_{0}$ is a solution of the equation $B w_{0}=h$. This equation has a solution because the problem (19) with $\delta=0$ may be reduced to this.

In Sec. 2, when investigating the properties of $B$ we have established that

$$
\left(B w_{\delta 0}, w_{\delta 0}\right)=\int_{\Omega}\left|\operatorname{grad} v_{\delta}\right|^{2} d x
$$

In view of the Fridrichs inequality [7] we have

$$
\begin{equation*}
\left(B w_{\delta 0}, w_{\delta 0}\right) \geq C_{2}\left\|v_{\delta}\right\|_{L_{2}(\Omega)}^{2} \tag{25}
\end{equation*}
$$

On the other hand, since $z_{\delta}$ satisfies the last problem in (21) there holds the estimate

$$
\left\|z_{\delta}\right\|_{H^{2}(\Omega)} \leq\left\|v_{\delta}\right\|_{L_{2}(\Omega)}^{2}
$$

Hence, taking into account (25) and (24) we obtain

$$
\left\|z_{\delta}\right\|_{H^{2}(\Omega)} \leq C_{1}
$$

where $C_{1}=\sqrt{\frac{C_{3}}{C_{1}}\left(B w_{0}, w_{0}\right)}, C_{2}, C_{3}$ and $w_{0}$ being independent of $\delta$. Thus, the theorem is proved.

As usual (see [1-5]), we construct an approximate solution of the original problem (1)-(2) by the formula

$$
U^{E}=\sum_{i=1}^{N+1} \gamma_{i} u_{\delta / i}
$$

where

$$
\gamma_{i}=\frac{(-1)^{N+1-i} i^{N+1}}{i!(N+1-i)!}
$$

$u_{\delta / i}$ is the solution of (14) with the parameter $\delta / i(i=1, \ldots, N+1)$. Then, it is easy to obtain the following estimate

$$
\left\|U^{E}-u\right\|_{H^{2}(\Omega)} \leq C \delta^{N+1}
$$

where $u$ is the solution of (1)-(2), $C$ is a constant independent of $\delta$.
For solving (14), which may be reduced to the equation (15) we propose to use the following iterative process under the assumption $f \in L_{2}(\Omega)$ :
i) Give a start approximation $w_{\delta 0}^{(0)} \in H^{1 / 2}(\Gamma)$.
ii) Knowing $w_{\delta 0}^{(k)}, \quad(k=0,1, \ldots)$, solve successively three problems

$$
\begin{align*}
\Delta w_{\delta}^{(k)} & =f, \quad x \in \Omega,\left.\quad w_{\delta}^{(k)}\right|_{\Gamma}=w_{\delta 0}^{(k)}, \\
\Delta v_{\delta}^{(k)} & =w_{\delta}^{(k)}, \quad x \in \Omega,\left.\quad v_{\delta}^{(k)}\right|_{\Gamma}=0  \tag{26}\\
\Delta u_{\delta}^{(k)} & =v_{\delta}^{(k)}, \quad x \in \Omega,\left.\quad u_{\delta}^{(k)}\right|_{\Gamma}=0
\end{align*}
$$

iii) Compute the new approximation of $w_{\delta 0}$

$$
\begin{equation*}
\left.w_{\delta 0}^{(k+1)}=w_{\delta 0}^{(k)}-\tau_{\delta, k+1} \frac{\partial u_{\delta}^{(k)}}{\partial \nu} \right\rvert\, \Gamma, \quad x \in \Gamma \tag{27}
\end{equation*}
$$

where $\tau_{\delta, k+1}$ is the Chebyshev collection of parameters according to bounds $\gamma_{\delta}^{1}=\delta, \gamma_{\delta}^{2}=\delta+\|B\|$ (see $[1,8]$ for detail). In the case of simple iteration

$$
\tau_{\delta, k} \equiv \tau_{\delta, 0}=\frac{2}{\gamma_{\delta}^{1}+\gamma_{\delta}^{2}}
$$

we get

$$
\begin{equation*}
\left\|w_{\delta 0}^{(k)}-w_{\delta 0}\right\|_{H} \leq\left(\rho_{\delta}\right)^{k}\left\|w_{\delta 0}^{(0)}-w_{\delta 0}\right\|_{H} \tag{28}
\end{equation*}
$$

where

$$
\rho_{\delta}=\frac{1-\xi_{\delta}}{1+\xi_{\delta}}, \xi_{\delta}=\frac{\gamma_{\delta}^{(1)}}{\gamma_{\delta}^{(2)}}
$$

and as above $H=L_{2}(\Gamma)$.
This result follows from the general theory of two-layer iterative schemes [8], applied to the operator equation (15), which is obtained from (14). Using estimates for the solution of elliptic problems [5] and taking into account (28) we get the estimate

$$
\left\|u_{\delta}^{(k)}-u_{\delta}\right\|_{H^{5 / 2}(\Omega)} \leq C\left(\rho_{\delta}\right)^{k}\left\|w_{\delta 0}^{(0)}-w_{\delta 0}\right\|_{H}
$$

where $C$ is a constant independent of $\delta$ and $w_{\delta 0}=\left.\Delta^{2} u_{\delta}\right|_{\Gamma}$ as was mentioned in the beginning of the section.

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